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# **MELISSA**

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## **TECHNICAL NOTE : 73.4**

Nitrite control of the Nitrifying compartment  
SIMPLIFICATION OF THE STATE SYSTEM OF THE INTERNAL MODEL

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## Document Change Log

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1	0	June 2003	Original version

<b>ESA-ESTEC</b>	<b>MELISSA - Technical Note 73.4</b> <b>"Control of nitrite : Simplification of the state system of the internal model"</b>		June 2003
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Abbreviations or notations:

NH<sub>3</sub> : ammonia (gaseous or solvated)  
 NO<sub>2</sub> : nitrite ion  
 NO<sub>3</sub> : nitrate ion  
 SO<sub>4</sub> : sulphate ion  
 PO<sub>4</sub> : phosphate ion  
 N<sub>s</sub> : Nitrosomonas strain  
 N<sub>b</sub> : Nitrobacter strain  
 solv. : solvated = molecular form (not total form)  
 PC : Personal Computer  
 PLC : Programmable Logical Computer  
 CV : Controlled Variable  
 MV : Manipulated Variable  
 CST : Completely Stirred Tank

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# 1. INTRODUCTION

The state system of the internal model of the control is identical to the one of the simulated process, except the fact that the fixed bed of the model is considered as only one CST (Completely Stirred Tank) instead of a series of several CST's.

So, at the beginning of the study related to the control (elaboration, tuning of performance and robustness), it seemed natural to re-use the algorithm of the process itself and to apply it to the control. All the study was done with a controller written with Matlab® code. At the end the Matlab® code was translated into C language for its implementation in the computer of the pilot plant at UAB. But when tests of the C software were done on several compilers, it appeared that one of them (Watcom 10.6 compiler) was unable to allocate enough memory to run correctly the computation : the algorithm involves multiplication and inversion of rather huge matrices that needs more than 64 K-octet of contiguous memory.

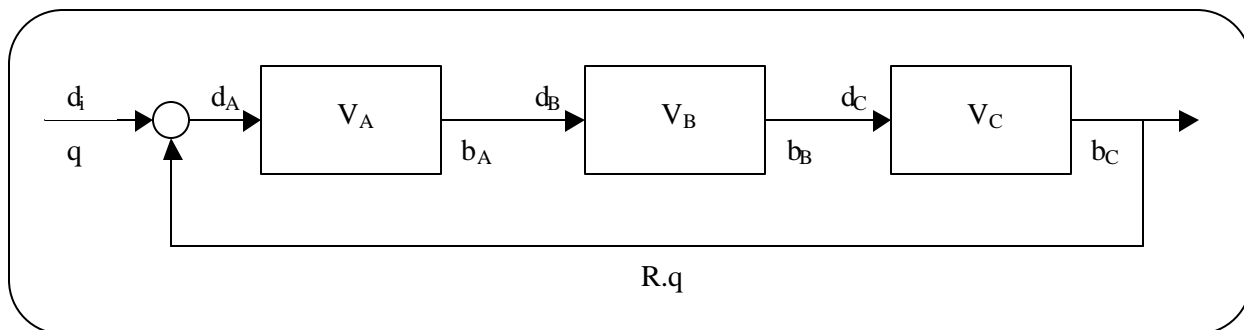
So as the column of the internal model is composed of 3 tanks only (parts A, B or fixed bed, and C of the column), it was decided to adapt the algorithm of the internal model to this specific case so that less memory is needed. Another advantage is a shorter computation time. The disadvantage is that the algorithm is not general and strictly devoted to a column with 3 tanks.

## 2. NEW ALGORITHM OF THE STATE SYSTEM

### 2.1. Case of the mono-phasis compounds

It is recalled that the mono-phasis compounds are the compounds only solvated in the liquid phasis and not present in the gas phasis :  $\text{NO}_2$ ,  $\text{NO}_3$ ,  $\text{SO}_4$  and  $\text{PO}_4$ .

The column of the internal model is represented by a series of 3 CST's where the dynamic behaviour is described by a first order transfer (figure 1). The back mixing ratios  $f_L$  of the 3 tanks are assumed null in the internal model.



**Figure 1 : Scheme of the column for the mono-phasis compounds**

**A,B,C : indices of the 3 parts**

**d : concentration of a compound at input of a tank**

**$d_i$  : concentration of a compound at input of the column**

**b : concentration of a compound at output of a tank**

**q : liquid flow rate**

**R : re-circulating ratio**

**V : volume**

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Given  $\theta = \frac{(1+R) \cdot q}{V}$  for any tank A, B or C.

Given  $r$  the variation rate of a compound.

The mass conservation implies the following set of equations for each mono-phasis compound :

$$\begin{aligned}
 \dot{b}_A &= -\theta_A \cdot b_A + \theta_A \cdot d_A + r_A \\
 \dot{b}_B &= -\theta_B \cdot b_B + \theta_B \cdot d_B + r_B \\
 \dot{b}_C &= -\theta_C \cdot b_C + \theta_C \cdot d_C + r_C \\
 (1+R) \cdot d_A &= d_i + R \cdot b_C \\
 d_B &= b_A \\
 d_C &= b_B
 \end{aligned} \tag{1}$$

Given the state vector  $X$  for a mono-phasis compound :

$$X = \begin{bmatrix} b_A \\ b_B \\ b_C \end{bmatrix}$$

The system (1) becomes :

$$\dot{X} = M_{AL} \cdot X + M_{BL} \cdot d_i + M_{EL} \cdot r_B \tag{2}$$

with

$$M_{AL} = \begin{bmatrix} -\theta_A & 0 & \theta_A \cdot \frac{R}{1+R} \\ \theta_B & -\theta_B & 0 \\ 0 & \theta_C & -\theta_C \end{bmatrix} \quad M_{BL} = \begin{bmatrix} \theta_A \cdot \frac{1}{1+R} \\ 0 \\ 0 \end{bmatrix} \quad M_{EL} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

In the relation (2) :

- $X$  is the vector of concentrations of a mono-phasis compound ( $NO_2$ ,  $NO_3$ ,  $SO_4$  or  $PO_4$ ) in the 3 tanks (A, B and C) of the column.
- the matrices  $M_{AL}$  and  $M_{BL}$  are independent of compound.
- $r_B$  is the variation rate in the fixed bed B and depends on the growth and maintenance law of  $N_s$  and  $N_b$  biomass. Its way of computation is unchanged in this study. The variation rates  $r_A$  and  $r_C$  are zero.

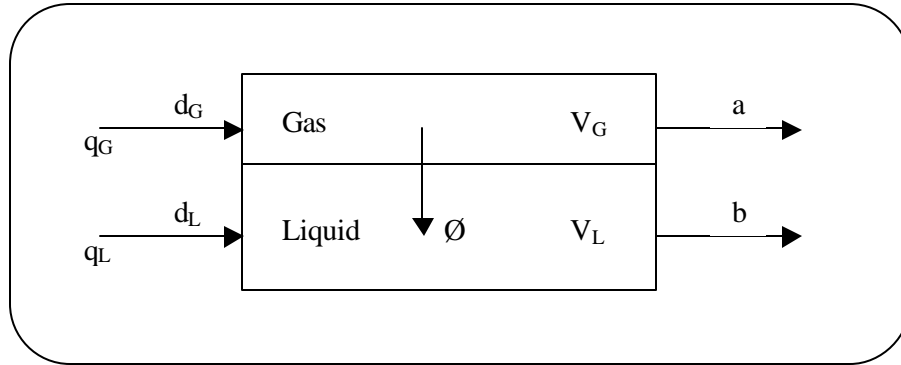
## 2.2. Case of the bi-phasis compounds

The bi-phasis compounds are the compounds present both in the liquid phasis and in the gas phasis :  $O_2$ ,  $CO_2$  and  $NH_3$ .

### 2.2.1. Recall of the mass conservation in one CST

The dynamic behaviour in a tank (figure 2) is described by a first order transfer in the gas and liquid volumes.

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**Figure 2 : Scheme of a tank for a bi-phasic compound**

The mass conservation implies the following set of equations :

$$a = \alpha \cdot c$$

$$\Phi = K \cdot (c - b)$$

$$V_G \cdot \dot{a} = -\Phi \cdot V_L + q_G \cdot (d_G - a)$$

$$V_L \cdot \dot{b} = (r + \Phi) \cdot \frac{V_L}{1+k} + q_L \cdot (d_L - b)$$

with  $\alpha$ : G/L equilibrium constant

$K$ :  $K_{La}$  (G/L transfer)

$k$ : dissociation constant

$c$ : concentration at thermodynamical equilibrium

$r$ : volumetric variation rate

(3)

The solution has been established in relations (9) and (10) of TN 44.2 :

$$\dot{b} = -\theta \cdot b + \theta_L \cdot d_L + \theta_G \cdot d_G + \theta_r \cdot r$$

$$a = \alpha_4 \cdot b + \alpha_5 \cdot d_G$$

(4)

$$\text{with : } \theta = \frac{1}{\tau_1} \quad \theta_L = \frac{G_1}{\tau_1} \quad \theta_G = \frac{G_2}{\tau_1} \quad \theta_r = \frac{G_3}{\tau_1}$$

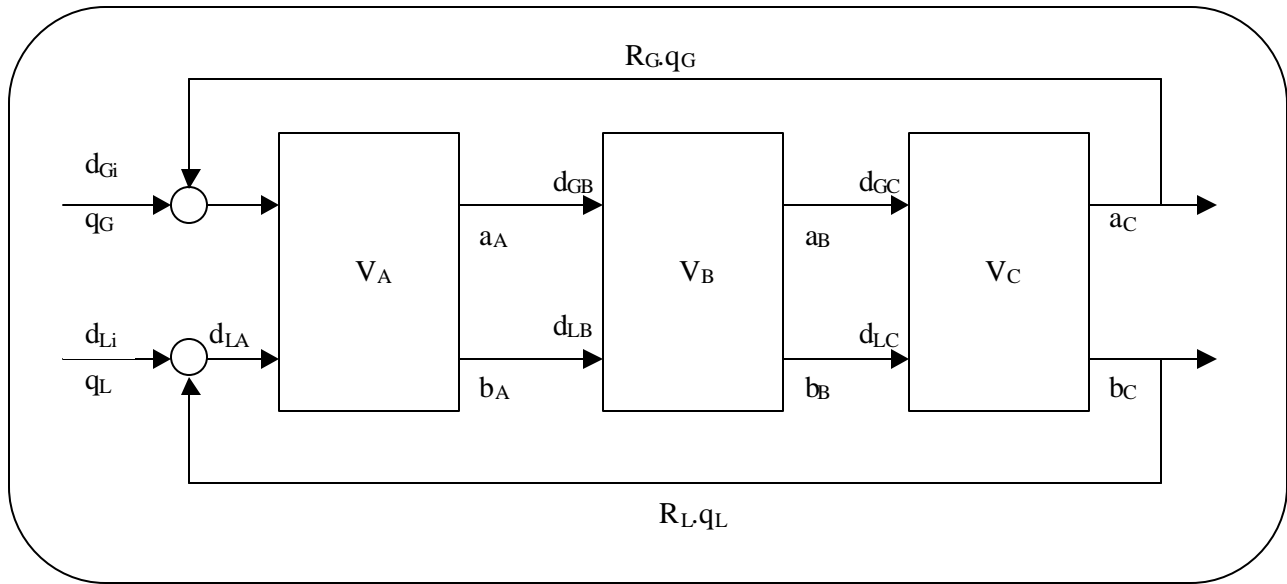
The expressions of  $G_1, G_2, G_3, \alpha_4, \alpha_5, \tau_1$  are given in (A2.2) (A2.8) of TN 44.2 .

The parameters  $\theta, \theta_L, \theta_G$  and  $\theta_r$  of (4) depend on tank (A, B or C) and on compound.

### 2.2.2. Mass conservation in the column

The column of the internal model is represented by a series of 3 CST's (figure 3). The back mixing ratios  $f_G$  and  $f_L$  are assumed null in the internal model.

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**Figure 3 : Scheme of the column for the bi-phase compounds**

**A,B,C : indices of the 3 parts**

**G, L = indices for Gas and Liquid phase**

**d : concentration of a compound at input of a tank**

**$d_i$  : concentration of a compound at input of the column**

**a : concentration of a G phase compound at output of a tank**

**b : concentration of a L phase compound at output of a tank**

**q : liquid flow rate**

**R : re-circulating ratio**

**V : volume**

Applying (4) to each tank A, B and C leads to the 3 sets of equations (5), (6) and (7) :

$$\begin{aligned}
 \dot{b}_A &= -\theta_A \cdot b_A + \theta_{LA} \cdot d_{LA} + \theta_{GA} \cdot d_{GA} + \theta_{rA} \cdot r_A \\
 a_A &= \alpha_{4A} \cdot b_A + \alpha_{5A} \cdot d_{GA} \\
 (1 + R_L) \cdot d_{LA} &= d_{Li} + R_L \cdot b_C \\
 (1 + R_G) \cdot d_{GA} &= d_{Gi} + R_G \cdot a_C
 \end{aligned} \tag{5}$$

$$\begin{aligned}
 \dot{b}_B &= -\theta_B \cdot b_B + \theta_{LB} \cdot d_{LB} + \theta_{GB} \cdot d_{GB} + \theta_{rB} \cdot r_B \\
 a_B &= \alpha_{4B} \cdot b_B + \alpha_{5B} \cdot d_{GB} \\
 d_{LB} &= b_A \\
 d_{GB} &= a_A
 \end{aligned} \tag{6}$$

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$$\begin{aligned}
\dot{b}_C &= -\theta_C \cdot b_C + \theta_{LC} \cdot d_{LC} + \theta_{GC} \cdot d_{GC} + \theta_{rC} \cdot r_C \\
a_C &= \alpha_{4C} \cdot b_C + \alpha_{5C} \cdot d_{GC} \\
d_{LC} &= b_B \\
d_{GC} &= a_C
\end{aligned} \tag{7}$$

Given the intermediate parameters :

$$\begin{aligned}
\alpha_{5G} &= 1 - \alpha_{5A} \cdot \alpha_{5B} \cdot \alpha_{5C} \cdot \frac{R_G}{1 + R_G} \\
p_1 &= \frac{\alpha_{4A} \cdot \alpha_{5B} \cdot \alpha_{5C}}{\alpha_{5G}} \cdot \frac{R_G}{1 + R_G} \\
p_2 &= \frac{\alpha_{4B} \cdot \alpha_{5C}}{\alpha_{5G}} \cdot \frac{R_G}{1 + R_G} \\
p_3 &= \frac{\alpha_{4C}}{\alpha_{5G}} \cdot \frac{R_G}{1 + R_G} \\
p_4 &= \frac{1}{\alpha_{5G}} \cdot \frac{1}{1 + R_G}
\end{aligned} \tag{8}$$

It has to be noted that  $\alpha_{5G}$  is strictly positive because  $R_G \geq 0$  and  $0 < \alpha_s < 1$  for A, B and C.

Given the state vector X and the vector of inputs U for a bi-phasis compound :

$$X = \begin{bmatrix} b_A \\ b_B \\ b_C \end{bmatrix} \quad U = \begin{bmatrix} d_{Gi} \\ d_{Li} \end{bmatrix}$$

The system (5) (6) (7) becomes (for a bi-phasis compound) :

$$\dot{X} = M_{AG} \cdot X + M_{BG} \cdot d_i + M_{EG} \cdot r_B \tag{9}$$

with

$$M_{AG} = \begin{bmatrix} -\theta_A + \theta_{GA} \cdot p_1 & \theta_{GA} \cdot p_2 & \theta_{LA} \cdot \frac{R_L}{1 + R_L} + \theta_{GA} \cdot p_3 \\ \theta_{LB} + \theta_{GB} \cdot (\alpha_{4A} + \alpha_{5A} \cdot p_1) & -\theta_B + \theta_{GB} \cdot \alpha_{5A} \cdot p_2 & \theta_{GB} \cdot \alpha_{5A} \cdot p_3 \\ \theta_{GC} \cdot \alpha_{5B} \cdot (\alpha_{4A} + \alpha_{5A} \cdot p_1) & \theta_{LC} + \theta_{GC} \cdot (\alpha_{4B} + \alpha_{5A} \cdot \alpha_{5B} \cdot p_2) & -\theta_C + \theta_{GC} \cdot \alpha_{5A} \cdot \alpha_{5B} \cdot p_3 \end{bmatrix}$$

$$M_{BG} = \begin{bmatrix} \theta_{GA} \cdot p_4 & \theta_{LA} \cdot \frac{1}{1 + R_L} \\ \theta_{GB} \cdot \alpha_{5A} \cdot p_4 & 0 \\ \theta_{GC} \cdot \alpha_{5A} \cdot \alpha_{5B} \cdot p_4 & 0 \end{bmatrix} \quad M_{EG} = \begin{bmatrix} 0 \\ \theta_{rB} \\ 0 \end{bmatrix}$$

In the relation (9) :

- X is the vector of concentrations of a bi-phasis compound (O<sub>2</sub>, CO<sub>2</sub> or NH<sub>3</sub>) in the 3 tanks (A, B and C) of the column.

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- the matrices  $M_{AG}$  ,  $M_{BG}$  and  $M_{EG}$  depend on compound through the thermodynamic constants.
- $r_B$  is the variation rate in the fixed bed B and depends on the growth and maintenance law of  $N_s$  and  $N_b$  biomass. Its way of computation is unchanged in this study. The variation rates  $r_A$  and  $r_C$  are zero.

### 2.3. Checking the algorithm

The new algorithm (annex) has been validated versus the previous one. There is no gap between the results of the 2 algorithms :

#### 2.3.1. Mono-phasis compounds

Gap between the 2 matrices A of mono-phasis compounds (MAL and As) :

```

0          0 -2.2204e-016
0          0          0
0          0          0

```

Gap between the 2 matrices B of mono-phasis compounds (MBL and Bs) :

```

0
0
0

```

#### 2.3.2. Bi-phasis compounds

----- Compound O2 -----

Gap between the 2 matrices A of bi-phasis compounds (MAG and As) :

```

0 -7.1054e-015 -1.7764e-015
-3.5527e-015 -2.8422e-014 -8.8818e-016
-5.3291e-015 -7.1054e-015          0

```

Gap between the 2 matrices B of bi-phasis compounds (MBG and Bs) :

```

-1.7764e-015          0
-8.8818e-016          0
-1.7764e-015          0

```

Gap between the 2 matrices E of bi-phasis compounds (MEG and Es) :

```

0
0
0

```

----- Compound CO2 -----

Gap between the 2 matrices A of bi-phasis compounds (MAG and As) :

```

0 -3.3307e-016          0
0 -4.4409e-016          0
0          0          0

```

Gap between the 2 matrices B of bi-phasis compounds (MBG and Bs) :

```

-5.5511e-017          0
-5.5511e-017          0
-5.5511e-017          0

```

Gap between the 2 matrices E of bi-phasis compounds (MEG and Es) :

```

0
0
0

```

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```

----- Compound NH3 -----
Gap between the 2 matrices A of bi-phasis compounds (MAG and As) :
      0 -8.6736e-019      0
      0      0 -4.3368e-019
      0      0      0

Gap between the 2 matrices B of bi-phasis compounds (MBG and Bs) :
      0      0
-6.9389e-018      0
      0      0

Gap between the 2 matrices E of bi-phasis compounds (MEG and Es) :
      0
      0
      0

```

### 3. CONCLUSION

The general algorithm for the computation of the state system has been established in relation (15) of TN 44.2 and is recalled hereafter :

$$\begin{cases} \dot{X} = A_e \cdot X + B_e \cdot U_0 + E \cdot J \cdot C_x \\ Y = C_e \cdot X + D_e \cdot U_0 \end{cases} \quad (10)$$

with :

$$\begin{aligned} A_e &= A - B(G \cdot D + H)^{-1} \cdot GC \\ C_e &= C - D(G \cdot D + H)^{-1} \cdot GC \\ B_e &= (2 \cdot N_G + N_L) \text{ first columns of } B(G \cdot D + H)^{-1} \\ D_e &= (2 \cdot N_G + N_L) \text{ first columns of } D(G \cdot D + H)^{-1} \end{aligned}$$

So, as it can be seen, the previous algorithm involved multiplication and inversion of matrices for the computation of  $A_e$  and  $B_e$ . In the new algorithm, the components of the matrices  $M_{AG}$ ,  $M_{AL}$ ,  $M_{BG}$  and  $M_{BL}$  are computed directly from the parameters of the internal model by means of relations (2) and (8).

Now concerning the memory allocation :

The size of the square matrix  $A_e$  was  $3 \cdot (N_G + N_L) \times 3 \cdot (N_G + N_L)$  where  $N_G$  and  $N_L$  are the number of bi and mono-phasis compounds ( $N_G=3$  and  $N_L=4$ ).

The size of  $B_e$  is  $3 \cdot (N_G + N_L) \times (2 \cdot N_G + N_L)$ .

In the new algorithm :

- $A_e$  is replaced by  $N_G$  matrices  $M_{AG}$  and 1 matrix  $M_{AL}$  whose sizes are  $3 \times 3$ . It implies that the total number of components is about 12 times as small.
- $B_e$  is replaced by  $N_G$  matrices  $M_{BG}$  of size  $3 \times 2$  and 1 matrix  $M_{BL}$  of size  $3 \times 1$ . It implies that the total number of components is divided by ten.

Then the size of arrays allocated in the memory of the computer for these matrices  $M_{AG}$ ,  $M_{AL}$ ,  $M_{BG}$  and  $M_{BL}$  is reduced considerably.

Moreover the matrices corresponding to the previous  $C_e$  and  $D_e$  need not to be computed because the concentrations in the gas are not necessary for the control.

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## 4. REFERENCE

LECLERCQ J.-J. : "Numerical simplification of the dynamic model of the nitrifying compartment ". Contract ESTEC n° 12924/98/NL/MV of July 10<sup>th</sup> 1998; May 1999; TN 44.2.

## 5. ANNEX : SOFTWARE OF COMPUTATION OF THE STATE SYSTEM

Source file of the Matlab® programme :

```

%*****
%      Nitrifying column control          *
%      Version 1.0      March 2003      *
%                                       *
%      State system according to TN 73.4 *
%                                       *
%      stasysim.m : Computation of the state system matrices *
%                  of the internal model of the control      *
%                                       *
%*****
function [MAG,MAL,MBG,MBL,MEG,MEL] = stasysim(NG, Gin, Fin, VA, VB, VC, epsG, epsL, ...
                                             epsT, RG, RL, KLa, Kdis, alpha)

% Computation of the matrices 'A' and 'B' dedicated to the biphasis compounds
G1=zeros(1,NG);
G2=zeros(1,NG);
G3=zeros(1,NG);
a4=zeros(1,NG);
a5=zeros(1,NG);
tau=zeros(1,NG);
NT=3; % Number of compartments of the column (case of internal model)
MAG=zeros(NT,NT,NG);
MBG=zeros(NT,2,NG); % 2=number of phases (G and L for the bi-phases compounds)
MEG=zeros(NT,NG);
for j=1:NG; % for biphasis compounds O2 CO2 and NH3
    for ii = 1:NT % for the differents parts of the column (case of internal model)
        if ii == 1 % Part A of the column
            VL = VA*epsL/epsT; % volume of liquid
            VG = VA*epsG/epsT; % volume of gas
            qL = Fin * (1+RL);
            qG = Gin * (1+RG);
        elseif ii == 2 % Part B of the column
            VL = VB*epsL; % volume of liquid
            VG = VB*epsG; % volume of gas
            qL = Fin * (1+RL);
            qG = Gin * (1+RG);
        elseif ii == 3 % Part C of the column
            VL = VC*epsL/epsT; % volume of liquid
            VG = VC*epsG/epsT; % volume of gas
            qL = Fin * (1+RL);
            qG = Gin * (1+RG);
        end

        % Computation of the gains G1, G2 ...
        [G1(ii),G2(ii),G3(ii),a4(ii),a5(ii),tau(ii),arret] = ...
            transbi(VG,VL,qG,qL,KLa(j),Kdis(j),alpha(j),ii);
    end

    t=1./tau;
    tL=G1./tau;
    tG=G2./tau;
    a5G=1-a5(1)*a5(2)*a5(3)*RG/(1+RG);
    % Intermediate parameters
    p1=a4(1)*a5(2)*a5(3)/a5G*RG/(1+RG);
    p2=a4(2)*a5(3)/a5G*RG/(1+RG);
    p3=a4(3)/a5G*RG/(1+RG);
    p4=1/(a5G*(1+RG));
    % Computation of the matrix 'A' dedicated to the biphasis compounds(matrix named 'MAG'
    hereafter)

```

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```

MAG(:,j)=[-t(1)+tG(1)*p1,          tG(1)*p2,
tL(1)*RL/(1+RL)+tG(1)*p3;
          tL(2)+tG(2)*(a4(1)+a5(1)*p1), -t(2)+tG(2)*a5(1)*p2,
tG(2)*a5(1)*p3;
          tG(3)*a5(2)*(a4(1)+a5(1)*p1), tL(3)+tG(3)*(a4(2)+a5(1)*a5(2)*p2), -
t(3)+tG(3)*a5(1)*a5(2)*p3];

% Computation of the matrix 'B' dedicated to the biphasis compounds(matrix named 'MBG'
hereafter)
MBG(:,j)=[tG(1)*p4,          tL(1)/(1+RL);
          tG(2)*a5(1)*p4,    0;
          tG(3)*a5(1)*a5(2)*p4, 0];

% Computation of the matrix 'E' dedicated to the biphasis compounds(matrix named 'MEG'
hereafter)
MEG(:,j)=[0;                % coef set to 0 because variation rate of compound is 0 in part A
          G3(2)/tau(2); % number 2 --> fixed bed (part B)
          0];                % coef set to 0 because variation rate of compound is 0 in part C
end

VL=[VA*epsL/epsT;          % volume of liquid of A
    VB*epsL;              % volume of liquid of B
    VC*epsL/epsT];        % volume of liquid of C

% Computation of the matrix 'A' dedicated to the monophasis compounds (matrix named 'MAL'
hereafter)
t=Fin*(1+RL)./VL;
MAL=[-t(1),          0, t(1)*RL/(1+RL);
      t(2), -t(2),          0;
      0, t(3),          -t(3)];

% Computation of the matrix 'B' dedicated to the monophasis compounds (matrix named 'MBL'
hereafter)
MBL=[t(1)/(1+RL); 0; 0];

% Computation of the matrix 'E' dedicated to the monophasis compounds (matrix named 'MEL'
hereafter)
MEL=[0; 1; 0];

if arret == 1, disp('*** Subroutine transbi called by stasysim ***'), end

```

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