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## TECHNICAL NOTE : 73.3

### Nitrite control of the Nitrifying compartment

AUTOMATIC CONVERSION OF THE SOFTWARE INTO C LANGUAGE

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<b>ESA-ESTEC</b>	<b>MELISSA - Technical Note 73.3</b>		June 2003
	<b>"Control of nitrite : Automatic conversion of the software into C langage"</b>		
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			Page 2

## TABLE OF CONTENTS

1. INTRODUCTION.....	4
2. DLL OR STAND-ALONE MATLAB APPLICATION .....	4
2.1. Introduction .....	4
2.2. Limitations .....	5
2.2.1. Compiler .....	5
2.2.1. Stand-alone application.....	5
2.2.3. Loading and saving files.....	6
2.3. Compiling.....	6
3. EXAMPLE OF APPLICATION.....	6
3.1. Description of the application .....	6
3.2. Results .....	7
4. CONCLUSION .....	8
5. REFERENCE .....	8
6. ANNEX : DETAILS OF THE APPLICATION EXAMPLE .....	9
6.1. Example of an original function written with Matlab langage .....	9
6.2. Converted files of the example function.....	11

Abbreviations or notations:

PC : Personal Computer  
 PLC : Programmable Logical Computer  
 CST : Completely Stirred Tank  
 DLL : Dynamic Link Library

ESA-ESTEC	MELISSA - Technical Note 73.3 "Control of nitrite : Automatic conversion of the software into C langage"		June 2003
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# 1. INTRODUCTION

The state system of the internal model of the control is identical to the one of the simulated process, except the fact that the fixed bed of the model is considered as only one CST (Completely Stirred Tank) instead of a series of several CST's.

So, at the beginning of the study related to the control (elaboration, tuning of performance and robustness), it seemed natural to re-use the algorithm of the process itself and to apply it to the control. All the study was done with a controller written with Matlab® code as it was easier that way to modify the code for comparing several approaches.

It was foreseen that, at the end and before its implementation in the computer of the pilot plant at UAB, the Matlab® code will be translated automatically into C language, using the tool '*Matlab Compiler*'.

According to the Matlab® documentation itself: "The Matlab Compiler automatically converts Matlab M-files to C and C++ code. The Matlab Compiler includes the Matlab C/C++ Math and Graphics Libraries, which allows the conversion of Matlab applications to C and C++ code for stand-alone applications".

This tool has been tested, before the nitrite controller was ready, on another application of the MELISSA project : the global simulator as it is achieved in the TN's 54.4 and 64.1 .

## 2. DLL OR STAND-ALONE MATLAB APPLICATION

### 2.1. Introduction

The DLL (mex-file) or stand-alone mode allows to use the Matlab functionalities (scientific computation, graphics ...) and to furnish to users an application independent of Matlab.

A mex-file and a stand-alone application differ in these respects :

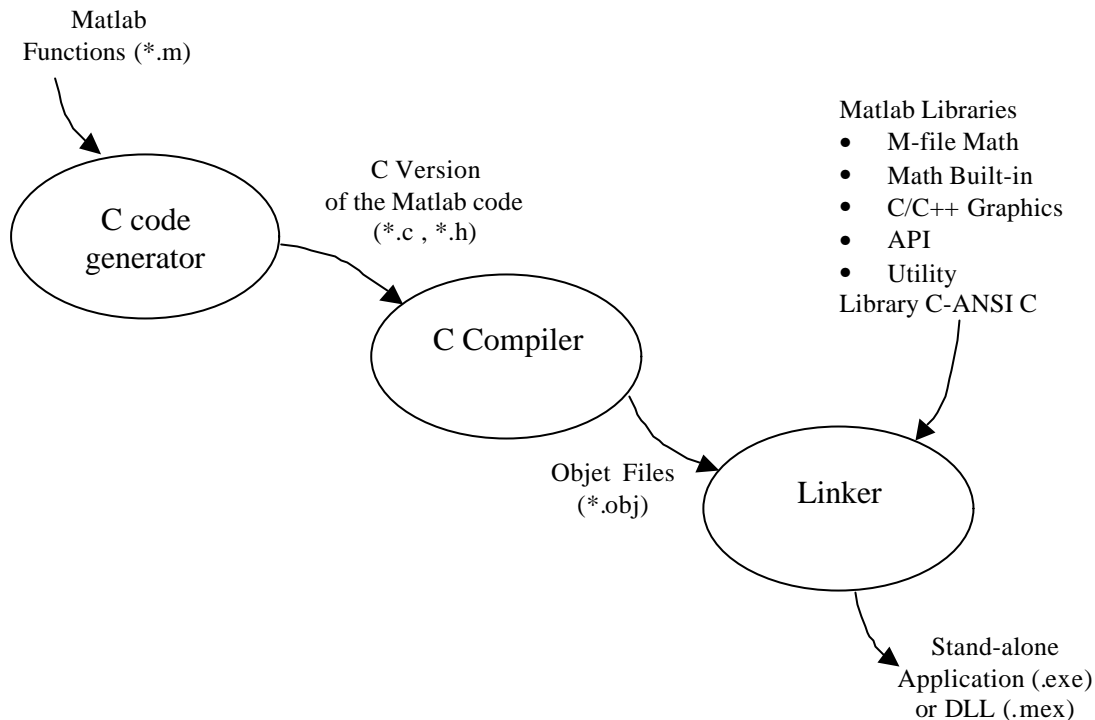
- a mex-file runs in the same process space as the Matlab interpreter. When a mex-file is invoked, the Matlab interpreter dynamically links in the mex-file.
- a stand-alone C or C++ application runs independently of Matlab.

In the present study, the test is done with a mex-file considering that the controller is connected with a process simulated with Matlab code.

The different steps of development of a stand-alone or DLL application follow (figure 1) :

- Elaboration of the application with Matlab language : writing of the Matlab functions in m-file only (Matlab scripts are forbidden);
- C code generation of each of the functions built in the previous step : this work is realized by the Matlab compiler;
- Compiling of the C functions (ANSI compiler)
- Linking with the Matlab libraries.

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**Figure 1 : Development of a stand-alone or DLL application**

## 2.2. Limitations

### 2.2.1. Compiler

The version of the Matlab Compiler supports nearly all the functionalities of Matlab. Nevertheless there are some limitations. The following Matlab cannot be compiled :

- Matlab scripts;
- Matlab files using objects;
- Matlab files using functions *input* or *eval*. However, when these functions do not use variables of the Work Space, they can be compiled.

### 2.2.1. Stand-alone application

The previous limitations are still true for stand-alone applications. Moreover the following functions of Table 1 are not supported.

add_block	add_line	applescript	assignin
callstats	close_system	cputime	dbclean
dbcont	dbdown	dbquit	dbstack
dbstatus	dbstep	dbstop	dbtype
dbup	delete_block	delete_line	diary
echo	edt	errorstat	errortrap
evalin	fields	fschange	functionscalled
get_param	hcreate	help	home
hregister	inferiorto	inmem	isglobal
isjava	isruntime	java	javaArray
javaMethod	javaObject	keyboard	linmod
lookfor	macprint	mactools	methods
mislocked	mlock	more	munlock

ESA-ESTEC	MELISSA - Technical Note 73.3		June 2003
	"Control of nitrite : Automatic conversion of the software into C langage"		
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			Page 5

new_system	open_system	pack	pfile
rehash	runtime	set_param	sim
simget	simset	sldebug	str2func
superiorto	system_dependent	trmginput	type
vms	what	which	who
whos			

**Table 1 : Functions non supported in stand-alone mode (from Matlab documentation)**

### 2.2.3. Loading and saving files

In the stand-alone mode, the functions *load* and *save* do not work when the variables of the file are defined. Particularly the specific loading does not work.

## 2.3. Compiling

When an application involves several functions, only the main function has to be declared to the compiler : the called functions will be compiled and linked automatically.

The following instructions are for C language. Analogue instructions exist for C++.

### **Building a mex-file :**

To build the C code of the Matlab function *TheApplication.m* and to create the associated mex-file (that has to be used with Matlab) :

```
mcc -x TheApplication
```

### **Building a stand-alone application :**

To build the C code of the Matlab function *TheApplication.m* and to create the associated stand-alone application (that can run without Matlab) :

```
mcc -m TheApplication
```

### **Building a stand-alone application with graphic:**

To build the C code of the Matlab function *TheApplication.m* which uses graphic functions and to create the associated stand-alone application (that can run without Matlab) :

```
mcc -B sgl TheApplication
```

## 3. EXAMPLE OF APPLICATION

### 3.1. Description of the application

As said in section 1, the Matlab Compiler is tested on the global simulator as it is achieved in the TN's 54.4 and 64.1 .

The programme of this global simulator is composed of 3 parts :

- a part for initializing of the parameters and arrays;
- another part composed of a loop calling the simulation of the process composed of the 5 compartments of the MELISSA project;
- and a third part of various statements (data process for plotting ...).

The programme can be represented by the following statements of a Matlab script file (fig. 2).

ESA-ESTEC	MELISSA - Technical Note 73.3 "Control of nitrite : Automatic conversion of the software into C langage"		June 2003
ADERSA	10, rue de la Croix Martre 91873 PALAISEAU Cedex	Tel : (33) 1 60 13 53 53 E-Mail : adersa@adersa.com	Fax : (33) 1 69 20 05 63 Page 6

```

InitializingStatements % Initialization of the programme
for i=1:n
    [OutputArguments]=simpro(InputArguments); % Process
    FurtherStatements1 % Complementary instructions group 1
end
FurtherStatements2 % Complementary instructions group 2

```

**Fig. 2 : Condensed form of the Matlab programme of the simulator**

As said in section 2, the script file of the fig.2 cannot be converted with the Matlab Compiler. But the function *simpro* can be.

The function *simpro* calls other various functions (Table 2) from Matlab library or not. Data are common to *simpro* and the Matlab Workspace by means of *global* statements.

Name	Function
simpro	: main function (to be translated in C language)
-stesta_2	: steady state of the Rhodo compartment
-rx_rhodo	: growth rate of Rhodo biomass
-cosh,sinh	: mathematical Matlab functions
-dich2_rh	: dichotomy algorithm
-pr_rhodo	: Rhodo process
-sqrt	: mathematical Matlab function (square root)
-stesta_3	: steady state of the Nitri compartment
-pr_nitri	: Nitri process
-irate	: instantaneous rate
-reshape	: Matlab function
-stesta_4	: steady state of the Spiru compartment
-rx_spiru	: growth rate of Spiru biomass
-stesta_5	: steady state of the Higher Plant compartment

**Table 2 : Sub-functions of *simpro***

### 3.2. Results

The Matlab Compiler converts each functions of the table 2 into corresponding '\*.h' and '\*.c' files : an example of conversion is given in annex. The conversion transforms the programme in such a way that it is no more understandable by a programmer. That could be considered redhibitory in the present study because if a problem occurs during execution on the target machine, it becomes nearly impossible to discover its origin, particularly if it comes from a Matlab function whose programme is unknown and inaccessible.

Then these files are compiled and linked to produce the mex-file of the function 'simpro'. No particular problems is encountered during that step.

The resulting application gives the same results as the original Matlab one.

As the resulting application is executable (and no more interpretable), a gain of running time was expected. That is confirmed but the gain is low (only 17 %) as reported in table 3.

Run number	Running time (s)		Gain (%)
	Compiled programme (mex)	Interpreted programme (Matlab)	
1	0.471	0.601	22
2	0.440	0.541	19
3	0.441	0.510	15
4	0.441	0.530	17
5	0.440	0.541	19
6	0.441	0.531	17
7	0.410	0.531	23
8	0.491	0.531	8
9	0.441	0.531	17
10	0.440	0.531	17
<b>Mean</b>	<b>0.4437</b>	<b>0.534</b>	<b>17</b>

**Table 3 : Comparison of running times of the 2 modes (mex and Matlab)**

#### 4. CONCLUSION

The Matlab Compiler has been tested on an application considered as representative of the controller (as that one was not ready at the moment of the test). Although the application is compiled instead of interpreted, the gain of running time is low.

The most interesting result is that the conversion transforms the original programme in such a way that it is no more understandable by a programmer. Moreover the Matlab functions (integration algorithms particularly) are inaccessible. Then if a problem occurs during the running on the target PLC, it would be impossible to analyze it. It is why the automatic conversion by means of the Matlab Compiler has been declared redhibitory in the case of the present study.

The conversion of the Matlab code of the nitrite controller will be done manually (step by step) in the TN 73.1 .

#### 5. REFERENCE

Matlab Compiler User's Guide. The MathWorks, Inc. September 2000. Revised for Version 2.1 (Release 12).



## 6. ANNEX : DETAILS OF THE APPLICATION EXAMPLE

### 6.1. Example of an original function written with Matlab language

Illustration of the function *simpro* (written with Matlab language) to be converted by the Matlab Compiler :

```
%*****
%      Connected compartments 0,1,2,3,4A and 4B (numbered 5 here)      *
%      Version 3.2      September 2002                                *
%                                                                 *
%      simpro.m      Simulation of the MELISSA loop (HPC included)    *
%      Open loop and Steady state                                    *
%                                                                 *
%*****
function [CG0_0, Y0_0, Y0_1, CG0_2, CL0_2, FR0_2, X0_2, Y0_2, ...
         CG0_3, CL0_3, X0_3, Y0_3, dX0_3, CG0_4, CL0_4, FR0_4, X0_4, Y0_4, ...
         CG0_5, CL0_5, Y0_5, ri_5] = ...
simpro(EE, fm_O2_0, fm_CO2_0, rO2_0, rCO2_0, initNH3, initNO2, initAcOH, initBuOH, ...
       initLiqueL, addCO2, addO2, Yx_AcOH, Y02_5, YCO2_5, spNO3_5, share2, cover)

global VM_0 Gin_0
global Gin_1 Fin_1 NG1_1 NG_1 NL_1 Kdis_1 rKdis_1 Yp_lp
global Gin_2 Fin_2 NG_2 NL_2 NO_2 NS_2 NI_2 NX_2 vNB_2 vNM_2 vNS_2 ...
       VL_2 Yx1_2 Kdis_2 KSSO4_2 A2_2 B2_2 GG1_2 GG2_2 ...
       FRmin_2 FRmax_2 fI_2 RT_2 Ea_2 Es_2 muM_2 KJ_2 EpsJ_2 q_rhod_2 zmin_I_2
global Gin_3 Fin_3 NL_3 NG_3 NS_3 NB_3 NX_3 NO_3 NI_3 NV_3 ...
       Ae_3 Be_3 Ce_3 De_3 E_3 WX_3 WYG_3 WYL_3 ...
       iO2_3 iCO2_3 iNH3_3 iNO2_3 iSub_3 iXNs_3 iXNb_3 iXag_3 ...
       KlnNs_3 KlnNb_3 KmNs_3 KmNb_3 mumax_3 maint_3 Yx_3 Yx1_3 Yml_3 ...
       RL_3 indG_3 indL_3 Kdis_3
global Fin_4 NG_4 NL_4 NO_4 vNB_4 vNM_4 VL_4 Yx1_4 Kdis_4 ...
       A2_4 B2_4 GG1_4 GG2_4 ...
       FRmin_4 FRmax_4 FRmaxc_4 fI_4 zPC_4 zCH_4 ...
       RT_4 Ea_4 Es_4 muM_4 muEPS_4 Kj_4 KJeps_4 Fmin_4 zmin_I_4 ...
       KSNO3_4 KSSO4_4 KSPO4_4 KSPC_4
global Gin_5 Fin_5 NG_5 NL_5 NS_5 VG_5 VL_5 Yx1e_5 Yx1w_5 Kdis_5 ...
       Diete_5 Dietw_5 A2_5 B2_5 ind_3u5
global idisp

%>>> CONSU
% Concentrations in the incoming Gas of Consu
% =====
CG0_0 = [fm_O2_0; fm_CO2_0]/VM_0; % mol/l of O2 CO2 going into Consu
% Initial output vector of Consu (static state)
% =====
Y0_0 = CG0_0 + [rO2_0; rCO2_0]/Gin_0;

%>>> LIQUE
% Concentrations in the incoming Gas and Liquid flows of Lique
% =====
%1. Gas phase : inert gas
%2. Liquid phase :
%cFaec_0 = qFaec_0/Fin_1; % mol/l
%cUrea_0 = qUrea_0/Fin_1; % mol/l
%cSO4_0 = qSO4_0/Fin_1; % mol/l
%cPO4_0 = qPO4_0/Fin_1; % mol/l
% Output vector of Lique (static state)
% =====
Y_1 = EE(2)*Yp_lp; % (mol/h): production rate of H2 CO2 NH3 AcOH BuOH
NY1= NG1_1+2*NG_1;
NY = NY1+NL_1;
% Gas concentration in mol/l (H2 and CO2 are totally under Gas phase)
Y0_1 = zeros(NY,1);
Y0_1(1:NG1_1) = Y_1(1:NG1_1)/Gin_1; % output conc. of H2 in Gas (mol/l)
```

MELISSA - Technical Note 73.3			June 2003
ESA-ESTEC	"Control of nitrite : Automatic conversion of the software into C langage"		
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```

% Liquid concentration in mol/l (CO2 NH3 AcOH & BuOH are totally in Liquid phase)
Y0_1(NY1+[1:4]) = Y_1(NY1+[1:4])/Fin_1./(1+Kdis_1(1:4)); % conc. in mol/l of CO2 NH3 molec.
form
Y0_1(NY1+5:NY) = initLiqueL; % conc. SO4 PO4 in mol/l

%>>> RHODO
% Initial concentrations in the incoming Gas and Liquid flows of Rhodo
% =====
%1. Gas phase (loop of inert gas) :
fm_CO2_2 = 0; % no CO2 (molar fraction)
fm_NH3_2 = 0; % no NH3 (molar fraction)
fm_Ac_2 = 0; % no AcOH (molar fraction)
fm_Bu_2 = 0; % no BuOH (molar fraction)
CG0_2 = [fm_CO2_2; fm_NH3_2; fm_Ac_2; fm_Bu_2] / VM_0; % mol/l
%2. Liquid phase :
%CL0_2 = [cCO2_0; cNH3_0; cAc_0; cBu_0; cSO4_0; cPO4_0] % mol/l
ind = [NY1+1:NY];
CL0_2 = Y0_1(ind).*rKdis_1; % mol/l of the molecular form CO2 NH3 AcOH BuOH
CL0_2(1:NG_2) = CL0_2(1:NG_2) + ...
    [YCO2_5; % addition of CO2 coming from HPC output
    initNH3; % NH3 GL coming from HPC output and going into L phase of Rhodo input
    initAcOH; % AcOH coming from L Rhodo output
    initBuOH]; % BuOH coming from L Rhodo output
% Initial concentration of biomass in Rhodo (to consume 'Yx_AcOH' part of AcOH load)
% =====
aa = 1 + Yx_AcOH*((1+Kdis_2(3))/(1+Kdis_2(NG_2))*Yx1_2(4,2)/Yx1_2(3,1) - 1);
cX0_2 = -Yx_AcOH * (1+Kdis_2(3)) / Yx1_2(3,1)* (aa*CL0_2(3)+CL0_2(NG_2)) / aa;
% Initial light flux and state vector of Rhodo (steady state)
% =====
%[FR0_2, X0_2, Y0_2] = stesta_2(...
% NG_2, NL_2, NO_2, vNB_2, vNM_2, VL_2, Fin_2, Yx1_2, KSSO4_2, ...
% A2_2, B2_2, GGI_2, GG2_2, CG0_2, CL0_2, cX0_2, ...
% FRmin_2, FRmax_2, fI_2, RT_2, Ea_2, Es_2, muM_2, KJ_2, EpsJ_2, q_rhod_2, zmin_I_2);
[FR0_2, X0_2, Y0_2, dX0_2] = stesta_2(...
    NG_2, NL_2, NO_2, NS_2, NI_2, NX_2, vNB_2, vNM_2, vNS_2, VL_2, Fin_2, Yx1_2, KSSO4_2, ...
    A2_2, B2_2, GGI_2, GG2_2, CG0_2, CL0_2, cX0_2, ...
    FRmin_2, FRmax_2, fI_2, RT_2, Ea_2, Es_2, muM_2, KJ_2, EpsJ_2, q_rhod_2, zmin_I_2);
%1. CO2 NH3 in G phase of Rhodo going into L phase of Rhodo :
X0_2(1:2) = X0_2(1:2) + (Y0_2(1:2)*Gin_2/Fin_2)./(1+Kdis_2(1:2)); % modif of state vector
%2. Modification of output vector
Y0_2(1:2) = zeros(2,1);
Y0_2(NG_2+[1:2]) = X0_2(1:2); % modif of output vector

%>>> NITRI
% Concentrations in the incoming Gas and Liquid flows of Nitri
% =====
%1. Gas phase (O2 CO2 from Consu, O2 used for H2 transformation) :
CG0_3 = [Y0_0; 0]; % mol/l of O2 CO2 NH3 (NH3:null) from Consu
CG0_3(1) = CG0_3(1) - Y_1(1)/2/Gin_3; %O2 used for H2 transformation
%2. Liquid phase (from Rhodo):
%CL0_3 = [C_O2_0; C_CO2_0; C_NH3_0; C_NO2_0; C_NO3_0; C_PO4_0; C_SO4_0];
CL0_3 = link2_3(X0_2)';
CL0_3(1) = YO2_5; % function of expected set point of O2_L at Spiru output
CL0_3(NG_3+2) = spNO3_5*Fin_5/Fin_3; % set point of NO3 at HPC output
CL0_3(NG_3+1) = CL0_3(NG_3+1) + initNO2; % NO2 from previous step
% Initial state and output vectors of Nitri (steady state)
% =====
if idisp, CG0_3,CL0_3,end
[X0_3, Y0_3, dX0_3] = stesta_3( ...
    NL_3, NG_3, NS_3, NB_3, NX_3, NO_3, NI_3, NV_3, ...
    Ae_3, Be_3, Ce_3, De_3, E_3, WX_3, WYG_3, WYL_3, ...
    iO2_3, iCO2_3, iNH3_3, iNO2_3, iSub_3, iXNs_3, iXNb_3, iXag_3, ...
    Klns_3, Klnb_3, KmNs_3, KmNb_3, mumax_3, maint_3, Yx_3, Yx1_3, Ym1_3, ...
    CG0_3, CL0_3, RL_3, indG_3, indL_3);
if isempty(X0_3), break, end
if idisp,X0_3p = [X0_3(indL_3);X0_3(indL_3(3)+1);X0_3(indL_3(3)+2)],end

%>>> SPIRU
% Initial concentrations in the incoming Gas and Liquid flows of Spiru
% =====
CGL0 = link3_4(Y0_3); % G and L from Nitri
%1. Gas phase :
CG0_4 = CGL0(1:NG_4); % mol/l

```

MELISSA - Technical Note 73.3			"Control of nitrite : Automatic conversion of the software into C langage"		June 2003
ESA-ESTEC	ADERSA	10, rue de la Croix Martre 91873 PALAISEAU Cedex	Tel : (33) 1 60 13 53 53 E-Mail : adersa@adersa.com	Fax : (33) 1 69 20 05 63	Page 10

```

%2. Liquid phase [O2 CO2 NO3 SO4 PO4]
CL0_4 = CGL0(NG_4+1:2*NG_4+NL_4); % mol/l
% Initial light flux and state vector of Spiru (steady state)
% =====
if idisp, CG0_4,CL0_4,end
[FR0_4, X0_4, Y0_4] = stesta_4( ...
    NG_4, NL_4, NO_4, vNB_4, vNM_4, Fin_4, VL_4, Yx1_4, ...
    A2_4, B2_4, GGI_4, GG2_4, CG0_4, CL0_4, EE(1), ...
    FRmin_4, FRmaxc_4, fI_4, zPC_4, zCH_4, ...
    RT_4, Ea_4, Es_4, muM_4, muEPS_4, Kj_4, KjEPS_4, Fmin_4, zmin_I_4, ...
    KSNO3_4, KSSO4_4, KSPO4_4, KSPC_4);
if (isempty(FR0_4) | isempty(X0_4)), break, end
if idisp, X0_4, FR0_4, end

%>>> HPC
% Concentrations in the incoming Gas and Liquid flows of HPC
% =====
%1. Gas phase [O2 CO2 NH3]:
indN1 = (NB_3+2)*NG_3; % index of NH3 G in output vector of Nitri
%CG0_5 = [Y0_4(1)+addO2/Gin_5;Y0_4(NG_4)+addCO2/Gin_5;Y0_3(indN1)]; % O2 CO2 NH3
CG0_5 = [Y0_4(1:NG_4)+[addO2;addCO2]/Gin_5;Y0_3(indN1)]; % O2 CO2 NH3
%2. Liquid phase [O2 CO2 NH3 NO3 SO4 PO4]
CL0_5 = link245(X0_2,Y0_3,X0_4,share2,NG_2,Kdis_2,...
    NG_3,ind_3u5,Kdis_3,NG_4,NL_4,Kdis_4,NG_5,Kdis_5);
% Initial state and variation rates vectors of HPC (steady state)
% =====
if idisp, CG0_5,CL0_5,end
[X0_5, ri_5] = stesta_5(...
    NG_5, NL_5, NS_5, VG_5, VL_5, Fin_5, Yx1e_5, Yx1w_5, ...
    Diete_5, Dietw_5, cover, A2_5, B2_5, CG0_5, CL0_5);
Y0_5=X0_5;
if idisp, Y0_5, end

```

## 6.2. Converted files of the example function

The conversion of the function *simpro* (written with Matlab language) produces 2 files : *simpro.h* and *simpro.c* far bigger than the original :

### *simpro.h* :

```

/*
 * MATLAB Compiler: 3.0
 * Date: Fri Sep 27 14:55:29 2002
 * Arguments: "-B" "macro_default" "-O" "all" "-O" "fold_scalar_mxarrays:on"
 * "-O" "fold_non_scalar_mxarrays:on" "-O" "optimize_integer_for_loops:on" "-O"
 * "array_indexing:on" "-O" "optimize_conditionals:on" "-O" "all" "-O"
 * "fold_scalar_mxarrays:on" "-O" "fold_non_scalar_mxarrays:on" "-O"
 * "optimize_integer_for_loops:on" "-O" "array_indexing:on" "-O"
 * "optimize_conditionals:on" "-x" "-W" "mex" "-L" "C" "-t" "-T"
 * "link:mexlibrary" "libmatlmbx.mlib" "-h" "-v" "-d" "compil" "simpro.m"
 */

#ifndef MLF_V2
#define MLF_V2 1
#endif

#ifndef __simpro_h
#define __simpro_h 1

#ifdef __cplusplus
extern "C" {
#endif

#include "libmatlb.h"

extern void InitializeModule_simpro(void);
extern void TerminateModule_simpro(void);
extern _mexLocalFunctionTable _local_function_table_simpro;

extern mxArray * mlfSimpro(mxArray ** Y0_0,
    mxArray ** Y0_1,

```

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```

mxArray * * CG0_2,
mxArray * * CL0_2,
mxArray * * FR0_2,
mxArray * * X0_2,
mxArray * * Y0_2,
mxArray * * CG0_3,
mxArray * * CL0_3,
mxArray * * X0_3,
mxArray * * Y0_3,
mxArray * * dX0_3,
mxArray * * CG0_4,
mxArray * * CL0_4,
mxArray * * FR0_4,
mxArray * * X0_4,
mxArray * * Y0_4,
mxArray * * CG0_5,
mxArray * * CL0_5,
mxArray * * Y0_5,
mxArray * * ri_5,
mxArray * EE,
mxArray * fm_O2_0,
mxArray * fm_CO2_0,
mxArray * rO2_0,
mxArray * rCO2_0,
mxArray * initNH3,
mxArray * initNO2,
mxArray * initAcOH,
mxArray * initBuOH,
mxArray * initLiqueL,
mxArray * addCO2,
mxArray * addO2,
mxArray * Yx_AcOH,
mxArray * YO2_5,
mxArray * YCO2_5,
mxArray * spNO3_5,
mxArray * share2,
mxArray * cover);
extern void mlxSimpro(int nlhs, mxArray * plhs[], int nrhs, mxArray * prhs[]);

#ifdef __cplusplus
}
#endif

#endif

simpro.c :
/*
 * MATLAB Compiler: 3.0
 * Date: Fri Sep 27 14:55:29 2002
 * Arguments: "-B" "macro_default" "-O" "all" "-O" "fold_scalar_mxarrays:on"
 * "-O" "fold_non_scalar_mxarrays:on" "-O" "optimize_integer_for_loops:on" "-O"
 * "array_indexing:on" "-O" "optimize_conditionals:on" "-O" "all" "-O"
 * "fold_scalar_mxarrays:on" "-O" "fold_non_scalar_mxarrays:on" "-O"
 * "optimize_integer_for_loops:on" "-O" "array_indexing:on" "-O"
 * "optimize_conditionals:on" "-x" "-W" "mex" "-L" "C" "-t" "-T"
 * "link:mexlibrary" "libmatlmbx.mlib" "-h" "-v" "-d" "compile" "simpro.m"
 */
#include "simpro.h"
#include "libmatlmb.h"
#include "link245.h"
#include "link2_3.h"
#include "link3_4.h"
#include "stesta_2.h"
#include "stesta_3.h"
#include "stesta_4.h"
#include "stesta_5.h"

extern mxArray * A2_2;
extern mxArray * A2_4;
extern mxArray * A2_5;
extern mxArray * Ae_3;

```

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```

extern mxArray * B2_2;
extern mxArray * B2_4;
extern mxArray * B2_5;
extern mxArray * Be_3;
extern mxArray * Ce_3;
extern mxArray * De_3;
extern mxArray * Diete_5;
extern mxArray * Dietw_5;
extern mxArray * E_3;
extern mxArray * Ea_2;
extern mxArray * Ea_4;
extern mxArray * EpsJ_2;
extern mxArray * Es_2;
extern mxArray * Es_4;
extern mxArray * FRmax_2;
extern mxArray * FRmaxc_4;
extern mxArray * FRmin_2;
extern mxArray * FRmin_4;
extern mxArray * Fin_1;
extern mxArray * Fin_2;
extern mxArray * Fin_3;
extern mxArray * Fin_4;
extern mxArray * Fin_5;
extern mxArray * Fmin_4;
extern mxArray * GG1_2;
extern mxArray * GG1_4;
extern mxArray * GG2_2;
extern mxArray * GG2_4;
extern mxArray * Gin_0;
extern mxArray * Gin_1;
extern mxArray * Gin_2;
extern mxArray * Gin_3;
extern mxArray * Gin_5;
extern mxArray * KJ_2;
extern mxArray * KSNO3_4;
extern mxArray * KSPC_4;
extern mxArray * KSPO4_4;
extern mxArray * KSSO4_2;
extern mxArray * KSSO4_4;
extern mxArray * Kdis_1;
extern mxArray * Kdis_2;
extern mxArray * Kdis_3;
extern mxArray * Kdis_4;
extern mxArray * Kdis_5;
extern mxArray * KjEPS_4;
extern mxArray * Kj_4;
extern mxArray * KINb_3;
extern mxArray * KINs_3;
extern mxArray * KmNb_3;
extern mxArray * KmNs_3;
extern mxArray * NB_3;
extern mxArray * NG1_1;
extern mxArray * NG_1;
extern mxArray * NG_2;
extern mxArray * NG_3;
extern mxArray * NG_4;
extern mxArray * NG_5;
extern mxArray * NI_2;
extern mxArray * NI_3;
extern mxArray * NL_1;
extern mxArray * NL_2;
extern mxArray * NL_3;
extern mxArray * NL_4;
extern mxArray * NL_5;
extern mxArray * NO_2;
extern mxArray * NO_3;
extern mxArray * NO_4;
extern mxArray * NS_2;
extern mxArray * NS_3;
extern mxArray * NS_5;
extern mxArray * NV_3;

```

<b>ESA-ESTEC</b>	<b>MELISSA - Technical Note 73.3</b>		June 2003
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```

extern mxArray * NX_2;
extern mxArray * NX_3;
extern mxArray * RL_3;
extern mxArray * RT_2;
extern mxArray * RT_4;
extern mxArray * VG_5;
extern mxArray * VL_2;
extern mxArray * VL_4;
extern mxArray * VL_5;
extern mxArray * VM_0;
extern mxArray * WX_3;
extern mxArray * WYG_3;
extern mxArray * WYL_3;
extern mxArray * Ym1_3;
extern mxArray * Yp_1p;
extern mxArray * Yx1_2;
extern mxArray * Yx1_3;
extern mxArray * Yx1_4;
extern mxArray * Yx1e_5;
extern mxArray * Yx1w_5;
extern mxArray * Yx_3;
extern mxArray * fI_2;
extern mxArray * fI_4;
extern mxArray * iCO2_3;
extern mxArray * iNH3_3;
extern mxArray * iNO2_3;
extern mxArray * iO2_3;
extern mxArray * iSub_3;
extern mxArray * iXNb_3;
extern mxArray * iXNs_3;
extern mxArray * iXag_3;
extern mxArray * idisp;
extern mxArray * indG_3;
extern mxArray * indL_3;
extern mxArray * ind_3u5;
extern mxArray * maint_3;
extern mxArray * muEPS_4;
extern mxArray * muM_2;
extern mxArray * muM_4;
extern mxArray * mumax_3;
extern mxArray * q_rhod_2;
extern mxArray * rKdis_1;
extern mxArray * vNB_2;
extern mxArray * vNB_4;
extern mxArray * vNM_2;
extern mxArray * vNM_4;
extern mxArray * vNS_2;
extern mxArray * zCH_4;
extern mxArray * zPC_4;
extern mxArray * zmin_I_2;
extern mxArray * zmin_I_4;
static mxArray * _mxarray0_;
static mxArray * _mxarray1_;

static double _array3_[4] = { 1.0, 2.0, 3.0, 4.0 };
static mxArray * _mxarray2_;
static mxArray * _mxarray4_;
static mxArray * _mxarray5_;
static mxArray * _mxarray6_;

static double _array8_[2] = { 1.0, 2.0 };
static mxArray * _mxarray7_;

void InitializeModule_simpro(void) {
    _mxarray0_ = mclInitializeDouble(2.0);
    _mxarray1_ = mclInitializeDouble(1.0);
    _mxarray2_ = mclInitializeDoubleVector(1, 4, _array3_);
    _mxarray4_ = mclInitializeDouble(4.0);
    _mxarray5_ = mclInitializeDouble(5.0);
    _mxarray6_ = mclInitializeDouble(0.0);
    _mxarray7_ = mclInitializeDoubleVector(1, 2, _array8_);
}

```

<b>ESA-ESTEC</b>	<b>MELISSA - Technical Note 73.3</b>		June 2003
	<b>"Control of nitrite : Automatic conversion of the software into C langage"</b>		
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			Page 14

```

}

void TerminateModule_simpro(void) {
  mxDestroyArray(_mxarray7_);
  mxDestroyArray(_mxarray6_);
  mxDestroyArray(_mxarray5_);
  mxDestroyArray(_mxarray4_);
  mxDestroyArray(_mxarray2_);
  mxDestroyArray(_mxarray1_);
  mxDestroyArray(_mxarray0_);
}

static mxArray * Msimpro(mxArray ** Y0_0,
  mxArray ** Y0_1,
  mxArray ** CG0_2,
  mxArray ** CL0_2,
  mxArray ** FR0_2,
  mxArray ** X0_2,
  mxArray ** Y0_2,
  mxArray ** CG0_3,
  mxArray ** CL0_3,
  mxArray ** X0_3,
  mxArray ** Y0_3,
  mxArray ** dX0_3,
  mxArray ** CG0_4,
  mxArray ** CL0_4,
  mxArray ** FR0_4,
  mxArray ** X0_4,
  mxArray ** Y0_4,
  mxArray ** CG0_5,
  mxArray ** CL0_5,
  mxArray ** Y0_5,
  mxArray ** ri_5,
  int nargout_,
  mxArray * EE,
  mxArray * fm_O2_0,
  mxArray * fm_CO2_0,
  mxArray * rO2_0,
  mxArray * rCO2_0,
  mxArray * initNH3,
  mxArray * initNO2,
  mxArray * initAcOH,
  mxArray * initBuOH,
  mxArray * initLiqueL,
  mxArray * addCO2,
  mxArray * addO2,
  mxArray * Yx_AcOH,
  mxArray * YO2_5,
  mxArray * YCO2_5,
  mxArray * spNO3_5,
  mxArray * share2,
  mxArray * cover);

```

```

_mexLocalFunctionTable _local_function_table_simpro
= { 0, (mexFunctionTableEntry *)NULL };

```

```

/*
 * The function "mlfSimpro" contains the normal interface for the "simpro"
 * M-function from file "j:\partage\c0-5_mb\simpro.m" (lines 1-163). This
 * function processes any input arguments and passes them to the implementation
 * version of the function, appearing above.
 */

```

```

mxArray * mlfSimpro(mxArray ** Y0_0,
  mxArray ** Y0_1,
  mxArray ** CG0_2,
  mxArray ** CL0_2,
  mxArray ** FR0_2,
  mxArray ** X0_2,
  mxArray ** Y0_2,
  mxArray ** CG0_3,
  mxArray ** CL0_3,

```

<b>ESA-ESTEC</b>	<b>MELISSA - Technical Note 73.3</b>		June 2003
	<b>"Control of nitrite : Automatic conversion of the software into C langage"</b>		
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			Page 15

```

mxArray ** X0_3,
mxArray ** Y0_3,
mxArray ** dX0_3,
mxArray ** CG0_4,
mxArray ** CL0_4,
mxArray ** FR0_4,
mxArray ** X0_4,
mxArray ** Y0_4,
mxArray ** CG0_5,
mxArray ** CL0_5,
mxArray ** Y0_5,
mxArray ** ri_5,
mxArray * EE,
mxArray * fm_O2_0,
mxArray * fm_CO2_0,
mxArray * rO2_0,
mxArray * rCO2_0,
mxArray * initNH3,
mxArray * initNO2,
mxArray * initAcOH,
mxArray * initBuOH,
mxArray * initLiqueL,
mxArray * addCO2,
mxArray * addO2,
mxArray * Yx_AcOH,
mxArray * Y02_5,
mxArray * YCO2_5,
mxArray * spNO3_5,
mxArray * share2,
mxArray * cover) {
int nargout = 1;
mxArray * CG0_0 = NULL;
mxArray * Y0_0__ = NULL;
mxArray * Y0_1__ = NULL;
mxArray * CG0_2__ = NULL;
mxArray * CL0_2__ = NULL;
mxArray * FR0_2__ = NULL;
mxArray * X0_2__ = NULL;
mxArray * Y0_2__ = NULL;
mxArray * CG0_3__ = NULL;
mxArray * CL0_3__ = NULL;
mxArray * X0_3__ = NULL;
mxArray * Y0_3__ = NULL;
mxArray * dX0_3__ = NULL;
mxArray * CG0_4__ = NULL;
mxArray * CL0_4__ = NULL;
mxArray * FR0_4__ = NULL;
mxArray * X0_4__ = NULL;
mxArray * Y0_4__ = NULL;
mxArray * CG0_5__ = NULL;
mxArray * CL0_5__ = NULL;
mxArray * Y0_5__ = NULL;
mxArray * ri_5__ = NULL;
mlfEnterNewContext(
21,
18,
Y0_0,
CG0_2,
CL0_2,
FR0_2,
X0_2,
Y0_2,
CG0_3,
CL0_3,
X0_3,
Y0_3,
dX0_3,
CG0_4,
CL0_4,
FR0_4,

```

<b>ESA-ESTEC</b>	<b>MELISSA - Technical Note 73.3</b>		June 2003
	<b>"Control of nitrite : Automatic conversion of the software into C langage"</b>		
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			Page 16



```

X0_4,
Y0_4,
CG0_5,
CL0_5,
Y0_5,
ri_5,
EE,
fm_O2_0,
fm_CO2_0,
rO2_0,
rCO2_0,
initNH3,
initNO2,
initAcOH,
initBuOH,
initLiqueL,
addCO2,
addO2,
Yx_AcOH,
YO2_5,
YCO2_5,
spNO3_5,
share2,
cover);
if (Y0_0 != NULL) {
    ++nargout;
}
if (Y0_1 != NULL) {
    ++nargout;
}
if (CG0_2 != NULL) {
    ++nargout;
}
if (CL0_2 != NULL) {
    ++nargout;
}
if (FR0_2 != NULL) {
    ++nargout;
}
if (X0_2 != NULL) {
    ++nargout;
}
if (Y0_2 != NULL) {
    ++nargout;
}
if (CG0_3 != NULL) {
    ++nargout;
}
if (CL0_3 != NULL) {
    ++nargout;
}
if (X0_3 != NULL) {
    ++nargout;
}
if (Y0_3 != NULL) {
    ++nargout;
}
if (dX0_3 != NULL) {
    ++nargout;
}
if (CG0_4 != NULL) {
    ++nargout;
}
if (CL0_4 != NULL) {
    ++nargout;
}
if (FR0_4 != NULL) {
    ++nargout;
}
if (X0_4 != NULL) {
    ++nargout;
}

```

ESA-ESTEC	<b>MELISSA - Technical Note 73.3</b> <b>"Control of nitrite : Automatic conversion of the software into C langage"</b>		June 2003
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```

}
if (Y0_4 != NULL) {
    ++nargout;
}
if (CG0_5 != NULL) {
    ++nargout;
}
if (CL0_5 != NULL) {
    ++nargout;
}
if (Y0_5 != NULL) {
    ++nargout;
}
if (ri_5 != NULL) {
    ++nargout;
}
}
CG0_0
= Msimpro(
    &Y0_0_,
    &Y0_1_,
    &CG0_2_,
    &CL0_2_,
    &FR0_2_,
    &X0_2_,
    &Y0_2_,
    &CG0_3_,
    &CL0_3_,
    &X0_3_,
    &Y0_3_,
    &dX0_3_,
    &CG0_4_,
    &CL0_4_,
    &FR0_4_,
    &X0_4_,
    &Y0_4_,
    &CG0_5_,
    &CL0_5_,
    &Y0_5_,
    &ri_5_,
    nargout,
    EE,
    fm_O2_0,
    fm_CO2_0,
    rO2_0,
    rCO2_0,
    initNH3,
    initNO2,
    initAcOH,
    initBuOH,
    initLiqueL,
    addCO2,
    addO2,
    Yx_AcOH,
    YO2_5,
    YCO2_5,
    spNO3_5,
    share2,
    cover);
mlfRestorePreviousContext(
    21,
    18,
    Y0_0,
    Y0_1,
    CG0_2,
    CL0_2,
    FR0_2,
    X0_2,
    Y0_2,
    CG0_3,
    CL0_3,
    X0_3,

```

<b>ESA-ESTEC</b>	<b>MELISSA - Technical Note 73.3</b>		June 2003
	<b>"Control of nitrite : Automatic conversion of the software into C langage"</b>		
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			Page 18

```

Y0_3,
dX0_3,
CG0_4,
CL0_4,
FR0_4,
X0_4,
Y0_4,
CG0_5,
CL0_5,
Y0_5,
ri_5,
EE,
fm_O2_0,
fm_CO2_0,
rO2_0,
rCO2_0,
initNH3,
initNO2,
initAcOH,
initBuOH,
initLiqueL,
addCO2,
addO2,
Yx_AcOH,
YO2_5,
YCO2_5,
spNO3_5,
share2,
cover);
if (Y0_0 != NULL) {
    mclCopyOutputArg(Y0_0, Y0_0__);
} else {
    mxDestroyArray(Y0_0__);
}
if (Y0_1 != NULL) {
    mclCopyOutputArg(Y0_1, Y0_1__);
} else {
    mxDestroyArray(Y0_1__);
}
if (CG0_2 != NULL) {
    mclCopyOutputArg(CG0_2, CG0_2__);
} else {
    mxDestroyArray(CG0_2__);
}
if (CL0_2 != NULL) {
    mclCopyOutputArg(CL0_2, CL0_2__);
} else {
    mxDestroyArray(CL0_2__);
}
if (FR0_2 != NULL) {
    mclCopyOutputArg(FR0_2, FR0_2__);
} else {
    mxDestroyArray(FR0_2__);
}
if (X0_2 != NULL) {
    mclCopyOutputArg(X0_2, X0_2__);
} else {
    mxDestroyArray(X0_2__);
}
if (Y0_2 != NULL) {
    mclCopyOutputArg(Y0_2, Y0_2__);
} else {
    mxDestroyArray(Y0_2__);
}
if (CG0_3 != NULL) {
    mclCopyOutputArg(CG0_3, CG0_3__);
} else {
    mxDestroyArray(CG0_3__);
}
if (CL0_3 != NULL) {
    mclCopyOutputArg(CL0_3, CL0_3__);
}

```

ESA-ESTEC	<b>MELISSA - Technical Note 73.3</b>		June 2003
	<b>"Control of nitrite : Automatic conversion of the software into C langage"</b>		
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			Page 19

```

} else {
    mxDestroyArray(CLO_3__);
}
if (X0_3 != NULL) {
    mclCopyOutputArg(X0_3, X0_3__);
} else {
    mxDestroyArray(X0_3__);
}
if (Y0_3 != NULL) {
    mclCopyOutputArg(Y0_3, Y0_3__);
} else {
    mxDestroyArray(Y0_3__);
}
if (dX0_3 != NULL) {
    mclCopyOutputArg(dX0_3, dX0_3__);
} else {
    mxDestroyArray(dX0_3__);
}
if (CG0_4 != NULL) {
    mclCopyOutputArg(CG0_4, CG0_4__);
} else {
    mxDestroyArray(CG0_4__);
}
if (CL0_4 != NULL) {
    mclCopyOutputArg(CL0_4, CL0_4__);
} else {
    mxDestroyArray(CL0_4__);
}
if (FR0_4 != NULL) {
    mclCopyOutputArg(FR0_4, FR0_4__);
} else {
    mxDestroyArray(FR0_4__);
}
if (X0_4 != NULL) {
    mclCopyOutputArg(X0_4, X0_4__);
} else {
    mxDestroyArray(X0_4__);
}
if (Y0_4 != NULL) {
    mclCopyOutputArg(Y0_4, Y0_4__);
} else {
    mxDestroyArray(Y0_4__);
}
if (CG0_5 != NULL) {
    mclCopyOutputArg(CG0_5, CG0_5__);
} else {
    mxDestroyArray(CG0_5__);
}
if (CL0_5 != NULL) {
    mclCopyOutputArg(CL0_5, CL0_5__);
} else {
    mxDestroyArray(CL0_5__);
}
if (Y0_5 != NULL) {
    mclCopyOutputArg(Y0_5, Y0_5__);
} else {
    mxDestroyArray(Y0_5__);
}
if (ri_5 != NULL) {
    mclCopyOutputArg(ri_5, ri_5__);
} else {
    mxDestroyArray(ri_5__);
}
return mlfReturnValue(CG0_0);
}

```

/\*

- \* The function "mlxSimpro" contains the feval interface for the "simpro"
- \* M-function from file "j:\partage\c0-5\_mb\simpro.m" (lines 1-163). The feval
- \* function calls the implementation version of simpro through this function.
- \* This function processes any input arguments and passes them to the

<b>ESA-ESTEC</b>	<b>MELISSA - Technical Note 73.3</b>		June 2003
	<b>"Control of nitrite : Automatic conversion of the software into C langage"</b>		
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			Page 20

```

* implementation version of the function, appearing above.
*/
void mxSimpro(int nlhs, mxArray * plhs[], int nrhs, mxArray * prhs[] ) {
    mxArray * mprhs[18];
    mxArray * mplhs[22];
    int i;
    if (nlhs > 22) {
        mlfError(
            mxCreateString(
                "Run-time Error: File: simpro Lin e: 9 Column: "
                "1 The function \"simpro\" was called with mor"
                "e than the declared number of outputs (22)."),
            NULL);
    }
    if (nrhs > 18) {
        mlfError(
            mxCreateString(
                "Run-time Error: File: simpro Line: 9 Column: "
                "1 The function \"simpro\" was called with mor"
                "e than the declared number of inputs (18)."),
            NULL);
    }
    for (i = 0; i < 22; ++i) {
        mplhs[i] = NULL;
    }
    for (i = 0; i < 18 && i < nrhs; ++i) {
        mprhs[i] = prhs[i];
    }
    for (; i < 18; ++i) {
        mprhs[i] = NULL;
    }
    mlfEnterNewContext(
        0,
        18,
        mprhs[0],
        mprhs[1],
        mprhs[2],
        mprhs[3],
        mprhs[4],
        mprhs[5],
        mprhs[6],
        mprhs[7],
        mprhs[8],
        mprhs[9],
        mprhs[10],
        mprhs[11],
        mprhs[12],
        mprhs[13],
        mprhs[14],
        mprhs[15],
        mprhs[16],
        mprhs[17]);
    mplhs[0]
    = Msimpro(
        &mplhs[1],
        &mplhs[2],
        &mplhs[3],
        &mplhs[4],
        &mplhs[5],
        &mplhs[6],
        &mplhs[7],
        &mplhs[8],
        &mplhs[9],
        &mplhs[10],
        &mplhs[11],
        &mplhs[12],
        &mplhs[13],
        &mplhs[14],
        &mplhs[15],
        &mplhs[16],
        &mplhs[17],

```

<b>ESA-ESTEC</b>	<b>MELISSA - Technical Note 73.3</b>		June 2003
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			Page 21

```

    &mplhs[18],
    &mplhs[19],
    &mplhs[20],
    &mplhs[21],
    nlhs,
    mprhs[0],
    mprhs[1],
    mprhs[2],
    mprhs[3],
    mprhs[4],
    mprhs[5],
    mprhs[6],
    mprhs[7],
    mprhs[8],
    mprhs[9],
    mprhs[10],
    mprhs[11],
    mprhs[12],
    mprhs[13],
    mprhs[14],
    mprhs[15],
    mprhs[16],
    mprhs[17]);
mlfRestorePreviousContext(
0,
18,
mprhs[0],
mprhs[1],
mprhs[2],
mprhs[3],
mprhs[4],
mprhs[5],
mprhs[6],
mprhs[7],
mprhs[8],
mprhs[9],
mprhs[10],
mprhs[11],
mprhs[12],
mprhs[13],
mprhs[14],
mprhs[15],
mprhs[16],
mprhs[17]);
plhs[0] = mplhs[0];
for (i = 1; i < 22 && i < nlhs; ++i) {
    plhs[i] = mplhs[i];
}
for (; i < 22; ++i) {
    mxDestroyArray(mplhs[i]);
}
}

/*
 * The function "Msimpro" is the implementation version of the "simpro"
 * M-function from file "j:\partage\c0-5_mb\simpro.m" (lines 1-163). It
 * contains the actual compiled code for that M-function. It is a static
 * function and must only be called from one of the interface functions,
 * appearing below.
 */
/*
 * % *****
 * %    Connected compartments 0,1,2,3,4A and 4B (numbered 5 here)    *
 * %    Version 3.2    September 2002                                *
 * %                                                                 *
 * %    simpro.m    Simulation of the MELISSA loop (HPC included)    *
 * %    Open loop and Steady state                                    *
 * %                                                                 *
 * % *****
 * function [CG0_0, Y0_0, Y0_1, CG0_2, CL0_2, FR0_2, X0_2, Y0_2, ...
 */

```

<b>ESA-ESTEC</b>	<b>MELISSA - Technical Note 73.3</b>		June 2003
	<b>"Control of nitrite : Automatic conversion of the software into C langage"</b>		
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			Page 22

```

static mxArray * Msimpro(mxArray ** Y0_0,
    mxArray ** Y0_1,
    mxArray ** CG0_2,
    mxArray ** CL0_2,
    mxArray ** FR0_2,
    mxArray ** X0_2,
    mxArray ** Y0_2,
    mxArray ** CG0_3,
    mxArray ** CL0_3,
    mxArray ** X0_3,
    mxArray ** Y0_3,
    mxArray ** dX0_3,
    mxArray ** CG0_4,
    mxArray ** CL0_4,
    mxArray ** FR0_4,
    mxArray ** X0_4,
    mxArray ** Y0_4,
    mxArray ** CG0_5,
    mxArray ** CL0_5,
    mxArray ** Y0_5,
    mxArray ** ri_5,
    int nargout_,
    mxArray * EE,
    mxArray * fm_O2_0,
    mxArray * fm_CO2_0,
    mxArray * rO2_0,
    mxArray * rCO2_0,
    mxArray * initNH3,
    mxArray * initNO2,
    mxArray * initAcOH,
    mxArray * initBuOH,
    mxArray * initLiqueL,
    mxArray * addCO2,
    mxArray * addO2,
    mxArray * Yx_AcOH,
    mxArray * YO2_5,
    mxArray * YCO2_5,
    mxArray * spNO3_5,
    mxArray * share2,
    mxArray * cover) {
mexLocalFunctionTable save_local_function_table_
    = mclSetCurrentLocalFunctionTable(&_local_function_table_simpro);
mxArray * CG0_0 = NULL;
mxArray * X0_5 = NULL;
mxArray * indN1 = NULL;
mxArray * CGL0 = NULL;
mxArray * X0_3p = NULL;
mxArray * dX0_2 = NULL;
mxArray * cX0_2 = NULL;
mxArray * aa = NULL;
mxArray * ind = NULL;
mxArray * fm_Bu_2 = NULL;
mxArray * fm_Ac_2 = NULL;
mxArray * fm_NH3_2 = NULL;
mxArray * fm_CO2_2 = NULL;
mxArray * NY = NULL;
mxArray * NY1 = NULL;
mxArray * Y_1 = NULL;
mxArray * ans = NULL;
mclCopyArray(&EE);
mclCopyArray(&fm_O2_0);
mclCopyArray(&fm_CO2_0);
mclCopyArray(&rO2_0);
mclCopyArray(&rCO2_0);
mclCopyArray(&initNH3);
mclCopyArray(&initNO2);
mclCopyArray(&initAcOH);
mclCopyArray(&initBuOH);
mclCopyArray(&initLiqueL);
mclCopyArray(&addCO2);
mclCopyArray(&addO2);

```

<b>ESA-ESTEC</b>	<b>MELISSA - Technical Note 73.3</b>		June 2003
	<b>"Control of nitrite : Automatic conversion of the software into C langage"</b>		
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			Page 23

```

mclCopyArray(&Yx_AcOH);
mclCopyArray(&YO2_5);
mclCopyArray(&YCO2_5);
mclCopyArray(&spNO3_5);
mclCopyArray(&share2);
mclCopyArray(&cover);
/*
* CG0_3, CL0_3, X0_3, Y0_3, dX0_3, CG0_4, CL0_4, FR0_4, X0_4, Y0_4, ...
* CG0_5, CL0_5, Y0_5, ri_5] = ...
* simpro(EE, fm_O2_0, fm_CO2_0, rO2_0, rCO2_0, initNH3, initNO2, initAcOH, initBuOH, ...
* initLiqueL, addCO2, addO2, Yx_AcOH, YO2_5, YCO2_5, spNO3_5, share2, cover)
*
* global VM_0 Gin_0
* global Gin_1 Fin_1 NG1_1 NG_1 NL_1 Kdis_1 rKdis_1 Yp_1p
* global Gin_2 Fin_2 NG_2 NL_2 NO_2 NS_2 NI_2 NX_2 vNB_2 vNM_2 vNS_2 ...
* VL_2 Yx1_2 Kdis_2 KSSO4_2 A2_2 B2_2 GG1_2 GG2_2 ...
* FRmin_2 FRmax_2 fl_2 RT_2 Ea_2 Es_2 muM_2 KJ_2 EpsJ_2 q_rhod_2 zmin_I_2
* global Gin_3 Fin_3 NL_3 NG_3 NS_3 NB_3 NX_3 NO_3 NI_3 NV_3 ...
* Ae_3 Be_3 Ce_3 De_3 E_3 WX_3 WYG_3 WYL_3 ...
* iO2_3 iCO2_3 iNH3_3 iNO2_3 iSub_3 iXNs_3 iXNb_3 iXag_3 ...
* KINs_3 KINb_3 KmNs_3 KmNb_3 mumax_3 maint_3 Yx_3 Yx1_3 Ym1_3 ...
* RL_3 indG_3 indL_3 Kdis_3
* global Fin_4 NG_4 NL_4 NO_4 vNB_4 vNM_4 VL_4 Yx1_4 Kdis_4 ...
* A2_4 B2_4 GG1_4 GG2_4 ...
* FRmin_4 FRmax_4 FRmaxc_4 fl_4 zPC_4 zCH_4 ...
* RT_4 Ea_4 Es_4 muM_4 muEPS_4 Kj_4 KjEPS_4 Fmin_4 zmin_I_4 ...
* KSNO3_4 KSSO4_4 KSPO4_4 KSPC_4
* global Gin_5 Fin_5 NG_5 NL_5 NS_5 VG_5 VL_5 Yx1e_5 Yx1w_5 Kdis_5 ...
* Diete_5 Dietw_5 A2_5 B2_5 ind_3u5
* global idisp
*
* %>>> CONSU
* % Concentrations in the incoming Gas of Consu
* % =====
* CG0_0 = [fm_O2_0; fm_CO2_0]/VM_0; % mol/l of O2 CO2 going into Consu
*/
mLfAssign(
&CG0_0,
mclMrdivide(
mLfVertcat(
mclVa(fm_O2_0, "fm_O2_0"), mclVa(fm_CO2_0, "fm_CO2_0"), NULL),
mclVg(&VM_0, "VM_0")));
/*
* % Initial output vector of Consu (static state)
* % =====
* Y0_0 = CG0_0 + [rO2_0; rCO2_0]/Gin_0;
*/
mLfAssign(
Y0_0,
mclPlus(
mclVv(CG0_0, "CG0_0"),
mclMrdivide(
mLfVertcat(mclVa(rO2_0, "rO2_0"), mclVa(rCO2_0, "rCO2_0"), NULL),
mclVg(&Gin_0, "Gin_0"))));
/*
*
* %>>> LIQUE
* % Concentrations in the incoming Gas and Liquid flows of Lique
* % =====
* % 1. Gas phase : inert gas
* % 2. Liquid phase :
* % cFaec_0 = qFaec_0/Fin_1; % mol/l
* % cUrea_0 = qUrea_0/Fin_1; % mol/l
* % cSO4_0 = qSO4_0/Fin_1; % mol/l
* % cPO4_0 = qPO4_0/Fin_1; % mol/l
* % Output vector of Lique (static state)
* % =====
* Y_1 = EE(2)*Yp_1p; % (mol/h): production rate of H2 CO2 NH3 AcOH BuOH
*/
mLfAssign(
&Y_1,

```

<b>ESA-ESTEC</b>	<b>MELISSA - Technical Note 73.3</b>		June 2003
	<b>"Control of nitrite : Automatic conversion of the software into C langage"</b>		
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			Page 24



```

mclMtimes(mclIntArrayRef1(mclVa(Ee, "Ee"), 2), mclVg(&Yp_1p, "Yp_1p"));
/*
* NY1= NG1_1+2*NG_1;
*/
mclAssign(
  &NY1,
  mclPlus(
    mclVg(&NG1_1, "NG1_1"), mclMtimes(_mxarray0_, mclVg(&NG_1, "NG_1"))));
/*
* NY = NY1+NL_1;
*/
mclAssign(&NY, mclPlus(mclVv(NY1, "NY1"), mclVg(&NL_1, "NL_1")));
/*
* % Gas concentration in mol/l (H2 and CO2 are totally under Gas phase)
* Y0_1 = zeros(NY,1);
*/
mclAssign(Y0_1, mclZeros(mclVv(NY, "NY"), _mxarray1_, NULL));
/*
* Y0_1(1:NG1_1) = Y_1(1:NG1_1)/Gin_1; % output conc. of H2 in Gas (mol/l)
*/
mclArrayAssign1(
  Y0_1,
  mclMrdivide(
    mclArrayRef1(
      mclVv(Y_1, "Y_1"),
      mclColon(_mxarray1_, mclVg(&NG1_1, "NG1_1"), NULL)),
    mclVg(&Gin_1, "Gin_1"),
    mclColon(_mxarray1_, mclVg(&NG1_1, "NG1_1"), NULL));
/*
* % Liquid concentration in mol/l (CO2 NH3 AcOH & BuOH are totally in Liquid phase)
* Y0_1(NY1+[1:4]) = Y_1(NY1+[1:4])/Fin_1./(1+Kdis_1(1:4)); % conc. in mol/l of CO2 NH3 molec. form
*/
mclArrayAssign1(
  Y0_1,
  mclRdivide(
    mclMrdivide(
      mclArrayRef1(
        mclVv(Y_1, "Y_1"), mclPlus(mclVv(NY1, "NY1"), _mxarray2_)),
        mclVg(&Fin_1, "Fin_1")),
    mclPlus(
      _mxarray1_,
      mclArrayRef1(
        mclVg(&Kdis_1, "Kdis_1"), mclColon(_mxarray1_, _mxarray4_, NULL))));
/*
* Y0_1(NY1+5:NY) = initLiqueL; % conc. SO4 PO4 in mol/l
*/
mclArrayAssign1(
  Y0_1,
  mclVa(initLiqueL, "initLiqueL"),
  mclColon(mclPlus(mclVv(NY1, "NY1"), _mxarray5_), mclVv(NY, "NY"), NULL));
/*
*
* %>>> RHODO
* % Initial concentrations in the incoming Gas and Liquid flows of Rhodo
* % =====
* % 1. Gas phase (loop of inert gas) :
* fm_CO2_2 = 0; % no CO2 (molar fraction)
*/
mclAssign(&fm_CO2_2, _mxarray6_);
/*
* fm_NH3_2 = 0; % no NH3 (molar fraction)
*/
mclAssign(&fm_NH3_2, _mxarray6_);
/*
* fm_Ac_2 = 0; % no AcOH (molar fraction)
*/
mclAssign(&fm_Ac_2, _mxarray6_);
/*
* fm_Bu_2 = 0; % no BuOH (molar fraction)
*/

```

<b>ESA-ESTEC</b>	<b>MELISSA - Technical Note 73.3</b>		June 2003
	<b>"Control of nitrite : Automatic conversion of the software into C langage"</b>		
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			Page 25



```

        mclIntArrayRef2(mclVg(&Yx1_2, "Yx1_2"), 4, 2)),
        mclIntArrayRef2(mclVg(&Yx1_2, "Yx1_2"), 3, 1)),
        _mxarray1_1));
*/
* cX0_2 = -Yx_AcOH * (1+Kdis_2(3)) / Yx1_2(3,1) * (aa*CL0_2(3)+CL0_2(NG_2)) / aa;
*/
mLfAssign(
&cX0_2,
mclMrdivide(
mclMtimes(
mclMrdivide(
mclMtimes(
mclUminus(mclVa(Yx_AcOH, "Yx_AcOH")),
mclPlus(
_mxarray1_1, mclIntArrayRef1(mclVg(&Kdis_2, "Kdis_2"), 3))),
mclIntArrayRef2(mclVg(&Yx1_2, "Yx1_2"), 3, 1)),
mclPlus(
mclMtimes(
mclVv(aa, "aa"), mclIntArrayRef1(mclVv(*CL0_2, "CL0_2"), 3)),
mclArrayRef1(mclVv(*CL0_2, "CL0_2"), mclVg(&NG_2, "NG_2")))),
mclVv(aa, "aa"));
*/
* % Initial light flux and state vector of Rhodo (steady state)
* % =====
* % [FR0_2, X0_2, Y0_2] = stesta_2(...)
* % NG_2, NL_2, NO_2, vNB_2, vNM_2, VL_2, Fin_2, Yx1_2, KSSO4_2, ...
* % A2_2, B2_2, GG1_2, GG2_2, CG0_2, CL0_2, cX0_2, ...
* % FRmin_2, FRmax_2, fl_2, RT_2, Ea_2, Es_2, muM_2, KJ_2, EpsJ_2, q_rhod_2, zmin_I_2);
* [FR0_2, X0_2, Y0_2, dX0_2] = stesta_2(...)
*/
mLfAssign(
FR0_2,
mLfStesta_2(
X0_2,
Y0_2,
&dX0_2,
mclVg(&NG_2, "NG_2"),
mclVg(&NL_2, "NL_2"),
mclVg(&NO_2, "NO_2"),
mclVg(&NS_2, "NS_2"),
mclVg(&NL_2, "NL_2"),
mclVg(&NX_2, "NX_2"),
mclVg(&vNB_2, "vNB_2"),
mclVg(&vNM_2, "vNM_2"),
mclVg(&vNS_2, "vNS_2"),
mclVg(&VL_2, "VL_2"),
mclVg(&Fin_2, "Fin_2"),
mclVg(&Yx1_2, "Yx1_2"),
mclVg(&KSSO4_2, "KSSO4_2"),
mclVg(&A2_2, "A2_2"),
mclVg(&B2_2, "B2_2"),
mclVg(&GG1_2, "GG1_2"),
mclVg(&GG2_2, "GG2_2"),
mclVv(*CG0_2, "CG0_2"),
mclVv(*CL0_2, "CL0_2"),
mclVv(cX0_2, "cX0_2"),
mclVg(&FRmin_2, "FRmin_2"),
mclVg(&FRmax_2, "FRmax_2"),
mclVg(&fl_2, "fl_2"),
mclVg(&RT_2, "RT_2"),
mclVg(&Ea_2, "Ea_2"),
mclVg(&Es_2, "Es_2"),
mclVg(&muM_2, "muM_2"),
mclVg(&KJ_2, "KJ_2"),
mclVg(&EpsJ_2, "EpsJ_2"),
mclVg(&q_rhod_2, "q_rhod_2"),
mclVg(&zmin_I_2, "zmin_I_2"));
*/
* NG_2, NL_2, NO_2, NS_2, NI_2, NX_2, vNB_2, vNM_2, vNS_2, VL_2, Fin_2, Yx1_2, KSSO4_2, ...
* A2_2, B2_2, GG1_2, GG2_2, CG0_2, CL0_2, cX0_2, ...
* FRmin_2, FRmax_2, fl_2, RT_2, Ea_2, Es_2, muM_2, KJ_2, EpsJ_2, q_rhod_2, zmin_I_2);

```

<b>ESA-ESTEC</b>	<b>MELISSA - Technical Note 73.3</b>		June 2003
	<b>"Control of nitrite : Automatic conversion of the software into C langage"</b>		
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			Page 27

```

* % 1. CO2 NH3 in G phase of Rhodo going into L phase of Rhodo :
* X0_2(1:2) = X0_2(1:2) + (Y0_2(1:2)*Gin_2/Fin_2)/(1+Kdis_2(1:2)); % modif of state vector
*/
mclArrayAssign1(
  X0_2,
  mclPlus(
    mclArrayRef1(
      mclVv(*X0_2, "X0_2"), mlfColon(_mxarray1_, _mxarray0_, NULL)),
    mclRdivide(
      mclMrdivide(
        mclMtimes(
          mclArrayRef1(
            mclVv(*Y0_2, "Y0_2"), mlfColon(_mxarray1_, _mxarray0_, NULL)),
            mclVg(&Gin_2, "Gin_2")),
          mclVg(&Fin_2, "Fin_2")),
        mclPlus(
          _mxarray1_,
          mclArrayRef1(
            mclVg(&Kdis_2, "Kdis_2"),
            mlfColon(_mxarray1_, _mxarray0_, NULL))))),
    mlfColon(_mxarray1_, _mxarray0_, NULL));
/*
* % 2. Modification of output vector
* Y0_2(1:2) = zeros(2,1);
*/
mclArrayAssign1(
  Y0_2,
  mlfZeros(_mxarray0_, _mxarray1_, NULL),
  mlfColon(_mxarray1_, _mxarray0_, NULL));
/*
* Y0_2(NG_2+[1:2]) = X0_2(1:2);          % modif of output vector
*/
mclArrayAssign1(
  Y0_2,
  mclArrayRef1(
    mclVv(*X0_2, "X0_2"), mlfColon(_mxarray1_, _mxarray0_, NULL)),
  mclPlus(mclVg(&NG_2, "NG_2"), _mxarray7_));
/*
*
* %>>> NITRI
* % Concentrations in the incoming Gas and Liquid flows of Nitri
* % =====
* % 1. Gas phase (O2 CO2 from Consu, O2 used for H2 transformation) :
* CG0_3 = [Y0_0; 0]; % mol/l of O2 CO2 NH3 (NH3:null) from Consu
*/
mlfAssign(CG0_3, mlfVertcat(mclVv(*Y0_0, "Y0_0"), _mxarray6_, NULL));
/*
* CG0_3(1) = CG0_3(1) - Y_1(1)/2/Gin_3; % O2 used for H2 transformation
*/
mclIntArrayAssign1(
  CG0_3,
  mclMinus(
    mclIntArrayRef1(mclVv(*CG0_3, "CG0_3"), 1),
    mclMrdivide(
      mclMrdivide(mclIntArrayRef1(mclVv(Y_1, "Y_1"), 1), _mxarray0_),
      mclVg(&Gin_3, "Gin_3"))),
  1);
/*
* % 2. Liquid phase (from Rhodo):
* % CL0_3 = [C_O2_0; C_CO2_0; C_NH3_0; C_NO2_0; C_NO3_0; C_PO4_0; C_SO4_0];
* CL0_3 = link2_3(X0_2);
*/
mlfAssign(CL0_3, mlfCtrnpose(mlfLink2_3(mclVv(*X0_2, "X0_2"))));
/*
* CL0_3(1) = YO2_5; % function of expected set point of O2_L at Spiru output
*/
mclIntArrayAssign1(CL0_3, mclVa(YO2_5, "YO2_5"), 1);
/*
* CL0_3(NG_3+2) = spNO3_5*Fin_5/Fin_3; % set point of NO3 at HPC output
*/
mclArrayAssign1(

```

<b>ESA-ESTEC</b>	<b>MELISSA - Technical Note 73.3</b>		June 2003
	<b>"Control of nitrite : Automatic conversion of the software into C langage"</b>		
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			Page 28

```

CL0_3,
mclMrdivide(
  mclMtimes(mclVa(spNO3_5, "spNO3_5"), mclVg(&Fin_5, "Fin_5")),
  mclVg(&Fin_3, "Fin_3")),
mclPlus(mclVg(&NG_3, "NG_3"), _marray0_);
/*
* CL0_3(NG_3+1) = CL0_3(NG_3+1) + initNO2; % NO2 from previous step
*/
mclArrayAssign1(
  CL0_3,
  mclPlus(
    mclArrayRef1(
      mclVv(*CL0_3, "CL0_3"), mclPlus(mclVg(&NG_3, "NG_3"), _marray1_),
      mclVa(initNO2, "initNO2")),
    mclPlus(mclVg(&NG_3, "NG_3"), _marray1_));
/*
* % Initial state and output vectors of Nitri (steady state)
* % =====
* if idisp, CG0_3,CL0_3,end
*/
if (mflTobool(mclVg(&idisp, "idisp"))) {
  mclPrintArray(mclVv(*CG0_3, "CG0_3"), "CG0_3");
  mclPrintArray(mclVv(*CL0_3, "CL0_3"), "CL0_3");
}
/*
* [X0_3, Y0_3, dX0_3] = stesta_3( ...
*/
mflAssign(
  X0_3,
  mflStesta_3(
    Y0_3,
    dX0_3,
    mclVg(&NL_3, "NL_3"),
    mclVg(&NG_3, "NG_3"),
    mclVg(&NS_3, "NS_3"),
    mclVg(&NB_3, "NB_3"),
    mclVg(&NX_3, "NX_3"),
    mclVg(&NO_3, "NO_3"),
    mclVg(&NI_3, "NI_3"),
    mclVg(&NV_3, "NV_3"),
    mclVg(&Ae_3, "Ae_3"),
    mclVg(&Be_3, "Be_3"),
    mclVg(&Ce_3, "Ce_3"),
    mclVg(&De_3, "De_3"),
    mclVg(&E_3, "E_3"),
    mclVg(&WX_3, "WX_3"),
    mclVg(&WYG_3, "WYG_3"),
    mclVg(&WYL_3, "WYL_3"),
    mclVg(&iO2_3, "iO2_3"),
    mclVg(&iCO2_3, "iCO2_3"),
    mclVg(&iNH3_3, "iNH3_3"),
    mclVg(&iNO2_3, "iNO2_3"),
    mclVg(&iSub_3, "iSub_3"),
    mclVg(&iXNs_3, "iXNs_3"),
    mclVg(&iXNb_3, "iXNb_3"),
    mclVg(&iXag_3, "iXag_3"),
    mclVg(&KINs_3, "KINs_3"),
    mclVg(&KINb_3, "KINb_3"),
    mclVg(&KmNs_3, "KmNs_3"),
    mclVg(&KmNb_3, "KmNb_3"),
    mclVg(&mumax_3, "mumax_3"),
    mclVg(&maint_3, "maint_3"),
    mclVg(&Yx_3, "Yx_3"),
    mclVg(&Yx1_3, "Yx1_3"),
    mclVg(&Ym1_3, "Ym1_3"),
    mclVv(*CG0_3, "CG0_3"),
    mclVv(*CL0_3, "CL0_3"),
    mclVg(&RL_3, "RL_3"),
    mclVg(&indG_3, "indG_3"),
    mclVg(&indL_3, "indL_3"));
/*

```

ESA-ESTEC	<b>MELISSA - Technical Note 73.3</b>		June 2003
	<b>"Control of nitrite : Automatic conversion of the software into C langage"</b>		
ADERSA	10, rue de la Croix Martre 91873 PALAISEAU Cedex	Tel : (33) 1 60 13 53 53 E-Mail : adersa@adersa.com	Fax : (33) 1 69 20 05 63 Page 29

```

* NL_3, NG_3, NS_3, NB_3, NX_3, NO_3, NI_3, NV_3, ...
* Ae_3, Be_3, Ce_3, De_3, E_3, WX_3, WYG_3, WYL_3, ...
* iO2_3, iCO2_3, iNH3_3, iNO2_3, iSub_3, iXNs_3, iXNb_3, iXag_3, ...
* KINs_3, KINb_3, KmNs_3, KmNb_3, mumax_3, maint_3, Yx_3, Yx1_3, Ym1_3, ...
* CG0_3, CL0_3, RL_3, indG_3, indL_3);
* if isempty(X0_3), break, end
*/
if (mLfTobool(mLfIsempty(mclVv(*X0_3, "X0_3")))) {
    goto return_;
}
/*
* if idisp,X0_3p = [X0_3(indL_3);X0_3(indL_3(3)+1);X0_3(indL_3(3)+2)],end
*/
if (mLfTobool(mclVg(&idisp, "idisp"))) {
    mlfAssign(
        &X0_3p,
        mlfVertcat(
            mclArrayRef1(mclVv(*X0_3, "X0_3"), mclVg(&indL_3, "indL_3")),
            mclArrayRef1(
                mclVv(*X0_3, "X0_3"),
                mclPlus(
                    mclIntArrayRef1(mclVg(&indL_3, "indL_3"), 3), _mxarray1_),
                mclArrayRef1(
                    mclVv(*X0_3, "X0_3"),
                    mclPlus(
                        mclIntArrayRef1(mclVg(&indL_3, "indL_3"), 3), _mxarray0_),
                        NULL));
            mclPrintArray(mclVv(X0_3p, "X0_3p"), "X0_3p");
        }
    /*
    * %>>> SPIRU
    * % Initial concentrations in the incoming Gas and Liquid flows of Spiru
    * % =====
    * CGL0 = link3_4(Y0_3); % G and L from Nitri
    */
    mlfAssign(&CGL0, mlfLink3_4(mclVv(*Y0_3, "Y0_3")));
    /*
    * % 1. Gas phase :
    * CG0_4 = CGL0(1:NG_4); % mol/l
    */
    mlfAssign(
        CG0_4,
        mclArrayRef1(
            mclVv(CGL0, "CGL0"), mlfColon(_mxarray1_, mclVg(&NG_4, "NG_4"), NULL));
    /*
    * % 2. Liquid phase [O2 CO2 NO3 SO4 PO4]
    * CL0_4 = CGL0(NG_4+1:2*NG_4+NL_4); % mol/l
    */
    mlfAssign(
        CL0_4,
        mclArrayRef1(
            mclVv(CGL0, "CGL0"),
            mlfColon(
                mclPlus(mclVg(&NG_4, "NG_4"), _mxarray1_),
                mclPlus(
                    mclMtimes(_mxarray0_, mclVg(&NG_4, "NG_4")), mclVg(&NL_4, "NL_4")),
                    NULL));
    /*
    * % Initial light flux and state vector of Spiru (steady state)
    * % =====
    * if idisp, CG0_4,CL0_4,end
    */
    if (mLfTobool(mclVg(&idisp, "idisp"))) {
        mclPrintArray(mclVv(*CG0_4, "CG0_4"), "CG0_4");
        mclPrintArray(mclVv(*CL0_4, "CL0_4"), "CL0_4");
    }
    /*
    * [FR0_4, X0_4, Y0_4] = stesta_4( ...
    */
    mlfAssign(
        FR0_4,

```

<b>ESA-ESTEC</b>	<b>MELISSA - Technical Note 73.3</b>		June 2003
	<b>"Control of nitrite : Automatic conversion of the software into C langage"</b>		
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			Page 30

```

mlfStesta_4(
  X0_4,
  Y0_4,
  mclVg(&NG_4, "NG_4"),
  mclVg(&NL_4, "NL_4"),
  mclVg(&NO_4, "NO_4"),
  mclVg(&vNB_4, "vNB_4"),
  mclVg(&vNM_4, "vNM_4"),
  mclVg(&Fin_4, "Fin_4"),
  mclVg(&VL_4, "VL_4"),
  mclVg(&Yx1_4, "Yx1_4"),
  mclVg(&A2_4, "A2_4"),
  mclVg(&B2_4, "B2_4"),
  mclVg(&GG1_4, "GG1_4"),
  mclVg(&GG2_4, "GG2_4"),
  mclVv(*CG0_4, "CG0_4"),
  mclVv(*CL0_4, "CL0_4"),
  mclIntArrayRef1(mclVa(EE, "EE"), 1),
  mclVg(&FRmin_4, "FRmin_4"),
  mclVg(&FRmaxc_4, "FRmaxc_4"),
  mclVg(&fl_4, "fl_4"),
  mclVg(&zPC_4, "zPC_4"),
  mclVg(&zCH_4, "zCH_4"),
  mclVg(&RT_4, "RT_4"),
  mclVg(&Ea_4, "Ea_4"),
  mclVg(&Es_4, "Es_4"),
  mclVg(&muM_4, "muM_4"),
  mclVg(&muEPS_4, "muEPS_4"),
  mclVg(&Kj_4, "Kj_4"),
  mclVg(&KjEPS_4, "KjEPS_4"),
  mclVg(&Fmin_4, "Fmin_4"),
  mclVg(&zmin_I_4, "zmin_I_4"),
  mclVg(&KSNO3_4, "KSNO3_4"),
  mclVg(&KSSO4_4, "KSSO4_4"),
  mclVg(&KSPO4_4, "KSPO4_4"),
  mclVg(&KSPC_4, "KSPC_4"));
/*
* NG_4, NL_4, NO_4, vNB_4, vNM_4, Fin_4, VL_4, Yx1_4, ...
* A2_4, B2_4, GG1_4, GG2_4, CG0_4, CL0_4, EE(1), ...
* FRmin_4, FRmaxc_4, fl_4, zPC_4, zCH_4, ...
* RT_4, Ea_4, Es_4, muM_4, muEPS_4, Kj_4, KjEPS_4, Fmin_4, zmin_I_4, ...
* KSNO3_4, KSSO4_4, KSPO4_4, KSPC_4);
* if (isempty(FR0_4) | isempty(X0_4)), break, end
*/
{
  mxArray * a_ = mclInitialize(mlfIsempty(mclVv(*FR0_4, "FR0_4")));
  if (mlfTobool(a_)
    || mlfTobool(mclOr(a_, mlfIsempty(mclVv(*X0_4, "X0_4"))))) {
    mxDestroyArray(a_);
    goto return_;
  } else {
    mxDestroyArray(a_);
  }
}
/*
* if idisp, X0_4, FR0_4, end
*/
if (mlfTobool(mclVg(&idisp, "idisp"))) {
  mclPrintArray(mclVv(*X0_4, "X0_4"), "X0_4");
  mclPrintArray(mclVv(*FR0_4, "FR0_4"), "FR0_4");
}
/*
*
* %>>> HPC
* % Concentrations in the incoming Gas and Liquid flows of HPC
* % =====
* % 1. Gas phase [O2 CO2 NH3]:
* indN1 = (NB_3+2)*NG_3; % index of NH3 G in output vector of Nitri
*/
mlfAssign(
  &indN1,

```

<b>ESA-ESTEC</b>	<b>MELISSA - Technical Note 73.3</b>		June 2003
	<b>"Control of nitrite : Automatic conversion of the software into C langage"</b>		
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			Page 31

```

mclMtimes(
  mclPlus(mclVg(&NB_3, "NB_3"), _marray0_), mclVg(&NG_3, "NG_3"));
/*
* %CG0_5 = [Y0_4(1)+addO2/Gin_5;Y0_4(NG_4)+addCO2/Gin_5;Y0_3(indN1)]; % O2 CO2 NH3
* CG0_5 = [Y0_4(1:NG_4)+[addO2;addCO2]/Gin_5;Y0_3(indN1)]; % O2 CO2 NH3
*/
mflAssign(
  CG0_5,
  mflVertcat(
    mclPlus(
      mclArrayRef1(
        mclVv(*Y0_4, "Y0_4"),
        mflColon(_marray1_, mclVg(&NG_4, "NG_4"), NULL)),
      mclMrdivide(
        mflVertcat(mclVa(addO2, "addO2"), mclVa(addCO2, "addCO2"), NULL),
        mclVg(&Gin_5, "Gin_5"))),
    mclArrayRef1(mclVv(*Y0_3, "Y0_3"), mclVv(indN1, "indN1")),
    NULL));
/*
* %2. Liquid phase [O2 CO2 NH3 NO3 SO4 PO4]
* CL0_5 = link245(X0_2,Y0_3,X0_4,share2,NG_2,Kdis_2,...
*/
mflAssign(
  CL0_5,
  mflLink245(
    mclVv(*X0_2, "X0_2"),
    mclVv(*Y0_3, "Y0_3"),
    mclVv(*X0_4, "X0_4"),
    mclVa(share2, "share2"),
    mclVg(&NG_2, "NG_2"),
    mclVg(&Kdis_2, "Kdis_2"),
    mclVg(&NG_3, "NG_3"),
    mclVg(&ind_3u5, "ind_3u5"),
    mclVg(&Kdis_3, "Kdis_3"),
    mclVg(&NG_4, "NG_4"),
    mclVg(&NL_4, "NL_4"),
    mclVg(&Kdis_4, "Kdis_4"),
    mclVg(&NG_5, "NG_5"),
    mclVg(&Kdis_5, "Kdis_5"));
/*
* NG_3,ind_3u5,Kdis_3,NG_4,NL_4,Kdis_4,NG_5,Kdis_5);
* % Initial state and variation rates vectors of HPC (steady state)
* % =====
* if idisp, CG0_5,CL0_5,end
*/
if (mflTobool(mclVg(&idisp, "idisp"))) {
  mclPrintArray(mclVv(*CG0_5, "CG0_5"), "CG0_5");
  mclPrintArray(mclVv(*CL0_5, "CL0_5"), "CL0_5");
}
/*
* [X0_5, ri_5] = stesta_5(...
*/
mflAssign(
  &X0_5,
  mflStesta_5(
    ri_5,
    mclVg(&NG_5, "NG_5"),
    mclVg(&NL_5, "NL_5"),
    mclVg(&NS_5, "NS_5"),
    mclVg(&VG_5, "VG_5"),
    mclVg(&VL_5, "VL_5"),
    mclVg(&Fin_5, "Fin_5"),
    mclVg(&Yx1e_5, "Yx1e_5"),
    mclVg(&Yx1w_5, "Yx1w_5"),
    mclVg(&Diete_5, "Diete_5"),
    mclVg(&Dietw_5, "Dietw_5"),
    mclVa(cover, "cover"),
    mclVg(&A2_5, "A2_5"),
    mclVg(&B2_5, "B2_5"),
    mclVv(*CG0_5, "CG0_5"),
    mclVv(*CL0_5, "CL0_5"));

```

<b>ESA-ESTEC</b>	<b>MELISSA - Technical Note 73.3</b>		June 2003
	<b>"Control of nitrite : Automatic conversion of the software into C langage"</b>		
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			Page 32



```

/*
* NG_5, NL_5, NS_5, VG_5, VL_5, Fin_5, Yx1e_5, Yx1w_5, ...
* Diete_5, Dietw_5, cover, A2_5, B2_5, CG0_5, CL0_5);
* Y0_5=X0_5;
*/
mlfAssign(Y0_5, mclVv(X0_5, "X0_5"));
/*
* if idisp, Y0_5, end
*/
if (mlfTobool(mclVg(&idisp, "idisp"))) {
    mclPrintArray(mclVv(*Y0_5, "Y0_5"), "Y0_5");
}
/*
*
*/
return_:
mclValidateOutput(CG0_0, 1, nargout_, "CG0_0", "simpro");
mclValidateOutput(*Y0_0, 2, nargout_, "Y0_0", "simpro");
mclValidateOutput(*Y0_1, 3, nargout_, "Y0_1", "simpro");
mclValidateOutput(*CG0_2, 4, nargout_, "CG0_2", "simpro");
mclValidateOutput(*CL0_2, 5, nargout_, "CL0_2", "simpro");
mclValidateOutput(*FR0_2, 6, nargout_, "FR0_2", "simpro");
mclValidateOutput(*X0_2, 7, nargout_, "X0_2", "simpro");
mclValidateOutput(*Y0_2, 8, nargout_, "Y0_2", "simpro");
mclValidateOutput(*CG0_3, 9, nargout_, "CG0_3", "simpro");
mclValidateOutput(*CL0_3, 10, nargout_, "CL0_3", "simpro");
mclValidateOutput(*X0_3, 11, nargout_, "X0_3", "simpro");
mclValidateOutput(*Y0_3, 12, nargout_, "Y0_3", "simpro");
mclValidateOutput(*dX0_3, 13, nargout_, "dX0_3", "simpro");
mclValidateOutput(*CG0_4, 14, nargout_, "CG0_4", "simpro");
mclValidateOutput(*CL0_4, 15, nargout_, "CL0_4", "simpro");
mclValidateOutput(*FR0_4, 16, nargout_, "FR0_4", "simpro");
mclValidateOutput(*X0_4, 17, nargout_, "X0_4", "simpro");
mclValidateOutput(*Y0_4, 18, nargout_, "Y0_4", "simpro");
mclValidateOutput(*CG0_5, 19, nargout_, "CG0_5", "simpro");
mclValidateOutput(*CL0_5, 20, nargout_, "CL0_5", "simpro");
mclValidateOutput(*Y0_5, 21, nargout_, "Y0_5", "simpro");
mclValidateOutput(*ri_5, 22, nargout_, "ri_5", "simpro");
mxDestroyArray(ans);
mxDestroyArray(Y_1);
mxDestroyArray(NY1);
mxDestroyArray(NY);
mxDestroyArray(fm_CO2_2);
mxDestroyArray(fm_NH3_2);
mxDestroyArray(fm_Ac_2);
mxDestroyArray(fm_Bu_2);
mxDestroyArray(ind);
mxDestroyArray(aa);
mxDestroyArray(cX0_2);
mxDestroyArray(dX0_2);
mxDestroyArray(X0_3p);
mxDestroyArray(CGL0);
mxDestroyArray(indN1);
mxDestroyArray(X0_5);
mxDestroyArray(cover);
mxDestroyArray(share2);
mxDestroyArray(spNO3_5);
mxDestroyArray(YCO2_5);
mxDestroyArray(YO2_5);
mxDestroyArray(Yx_AcOH);
mxDestroyArray(addO2);
mxDestroyArray(addCO2);
mxDestroyArray(initLiqueL);
mxDestroyArray(initBuOH);
mxDestroyArray(initAcOH);
mxDestroyArray(initNO2);
mxDestroyArray(initNH3);
mxDestroyArray(rCO2_0);
mxDestroyArray(rO2_0);
mxDestroyArray(fm_CO2_0);
mxDestroyArray(fm_O2_0);

```

<b>MELISSA - Technical Note 73.3</b>		<b>"Control of nitrite : Automatic conversion of the software into C langage"</b>		June 2003
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```

mxDestroyArray(EE);
mclSetCurrentLocalFunctionTable(save_local_function_table_);
return CG0_0;
}

```

<b>ESA-ESTEC</b>	<b>MELISSA - Technical Note 73.3</b> <b>"Control of nitrite : Automatic conversion of the software into C langage"</b>		June 2003
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